

TECHNOLOGY

Specification of Technology

- Input and Output can be specified in arbitrarily fine detail
- n possible goods can be used as input and/or output
- Net Output : $y_j = y_j^{output} - y_j^{input}$

$y_j > 0 \rightarrow$ net output, $y_j < 0 \rightarrow$ net input

- Production Plan = a list of net outputs, represented by a vector \mathbf{y} in R^n
- A Production Possibilities Set $Y =$ a set of all technologically feasible production plans

- Restrictions on production plans : e.g. a vector \mathbf{z} in R^n could be a list of a maximum amount of inputs and outputs that can be produced in a given time period.
- Restricted or Short-run production possibilities set $Y(\mathbf{z}) \subset Y$, e.g. factor n fixed at $\bar{y}_n \rightarrow Y(\bar{y}_n) = \{\mathbf{y} \text{ in } Y : y_n = \bar{y}_n\}$

Input Requirement Set :

$$V(y) = \{\mathbf{x} \text{ in } R_+^n : (y, -\mathbf{x}) \text{ is in } Y\}$$

is the set of all input bundles \mathbf{x} that produces at least y unit of output

Note: only one output y , net output is written as $(y, -\mathbf{x})$

Isoquant :

$$Q(y) = \{\mathbf{x} \text{ in } R_+^n : \mathbf{x} \text{ is in } V(y) \text{ and } \mathbf{x} \text{ is not in } V(y') \text{ for } y' > y\}$$

gives all input bundles that produces exactly y units of output

Production Function :

$f(\mathbf{x}) = \{y \text{ in } R : y \text{ is the maximum output associated with } -\mathbf{x} \text{ in } Y\}$

Technologically Efficient production plans :

y is technologically efficient if there is no \mathbf{y}' in Y such that $\mathbf{y}' \geq \mathbf{y}$ and $\mathbf{y}' \neq \mathbf{y}$

Transformation Function :

$T : R^n \rightarrow R$ where $T(\mathbf{y}) = 0$ iff y is efficient
can be used to describe a set of technologically efficient production plans.

It is an n -dimensional analog of a production function.

Example: **Cobb-Douglas Technology**

Let $0 < a < 1$

$$Y = \{(y, -x_1, -x_2) \text{ in } R^3 : y \leq x_1^a x_2^{1-a}\}$$

$$\begin{aligned}
V(y) &= \{(x_1, x_2) \text{ in } R_+^2: y \leq x_1^a x_2^{1-a}\} \\
Q(y) &= \{(x_1, x_2) \text{ in } R_+^2: y = x_1^a x_2^{1-a}\} \\
Y(z) &= \{(y, -x_1, -x_2) \text{ in } R^3: y \leq x_1^a x_2^{1-a}, x_2 = z\} \\
T(y, x_1, x_2) &= y - x_1^a x_2^{1-a} \\
f(x_1, x_2) &= x_1^a x_2^{1-a}
\end{aligned}$$

Example: **Leontief Technology**

Let $a > 0$ and $b > 0$

$$\begin{aligned}
Y &= \{(y, -x_1, -x_2) \text{ in } R^3: y \leq \min(ax_1, bx_2)\} \\
V(y) &= \{(x_1, x_2) \text{ in } R_+^2: y \leq \min(ax_1, bx_2)\} \\
Q(y) &= \{(x_1, x_2) \text{ in } R_+^2: y = \min(ax_1, bx_2)\} \\
T(y, x_1, x_2) &= y - \min(ax_1, bx_2) \\
f(x_1, x_2) &= \min(ax_1, bx_2)
\end{aligned}$$

Monotonic Technologies

Under free disposal, if \mathbf{x} is a feasible way to produce y and $\mathbf{x}' \geq \mathbf{x}$ should also be a feasible way to produce y

Monotonicity

For input requirement sets: If \mathbf{x} is in $V(y)$ and $\mathbf{x}' \geq \mathbf{x}$, then \mathbf{x}' is in $V(y)$

For production sets: If \mathbf{y} is in Y and $\mathbf{y}' \leq \mathbf{y}$, then \mathbf{y}' is in Y

\mathbf{y}' produces an equal or smaller amount of all outputs by using at least as much of all inputs compared to \mathbf{y}

Convex Technologies

Convexity

For input requirement sets: If \mathbf{x} and \mathbf{x}' are in $V(y)$, then $t\mathbf{x} + (1 - t)\mathbf{x}'$ is in $V(y)$ for all $0 \leq t \leq 1$

For production sets: If \mathbf{y} and \mathbf{y}' are in Y , then $t\mathbf{y} + (1 - t)\mathbf{y}'$ is in Y for all $0 \leq t \leq 1$

Convex production set implies convex input requirement set

Proof. If Y is a convex set and $(y, -\mathbf{x})$ and $(y, -\mathbf{x}')$ are in Y , then $(ty + (1 - t)y, -t\mathbf{x} - (1 - t)\mathbf{x}')$ must be in Y , i.e. $(y, -t\mathbf{x} - (1 - t)\mathbf{x}')$ is in Y

Hence, if \mathbf{x} and \mathbf{x}' are in $V(y)$, then $t\mathbf{x} + (1 - t)\mathbf{x}'$ is in $V(y)$.

Convex input requirement set is equivalent to quasiconcave production function

Proof. By definition, a function is quasiconcave iff it has a convex upper contour set. Since $V(y) = \{\mathbf{x} : f(\mathbf{x}) \geq y\}$ is the upper contour set of $f(\mathbf{x})$, then if $V(y)$ is convex, $f(\mathbf{x})$ is quasiconcave.

Regular Technologies

Regular

$V(y)$ is a closed and nonempty set for all $y \geq 0$

Nonempty \rightarrow there is a way to produce any given amount of output y

Closed $\rightarrow V(y)$ includes its own boundary. If a sequence of input bundles that can produce y converges to an input \mathbf{x}^0 then \mathbf{x}^0 must be capable of producing y

The Technical Rate of Substitution

The technical rate of substitution TRS measures how one of the inputs must adjust in order to keep output constant when another input changes. For 2-dimensional case, TRS measures the slope of the isoquant

$$\text{TRS of } x_2 \text{ for } x_1 = \frac{dx_2}{dx_1} = \frac{\partial f(\mathbf{x})/\partial x_1}{\partial f(\mathbf{x})/\partial x_2}$$

The Elasticity of Substitution

The elasticity of substitution measures the % change in the factor ratio divided by the % change in the TRS. The elasticity of substitution measures the curvature of the isoquant.

$$\text{Elasticity of substitution } \sigma = \frac{\Delta(x_2/x_1)}{x_2/x_1} / \frac{\Delta \text{TRS}}{\text{TRS}}$$

$$\text{For small change, } \sigma = \frac{d(x_2/x_1)}{x_2/x_1} / \frac{d\text{TRS}}{\text{TRS}} = \frac{\text{TRS}}{x_2/x_1} \frac{d(x_2/x_1)}{d\text{TRS}}$$

Homogeneity

For any scalar k , a function $f(x_1, \dots, x_2)$ is homogenous of degree k if

$$f(tx_1, \dots, tx_2) = t^k f(x_1, \dots, x_2) \text{ for all } x_1, \dots, x_2 \text{ and all } t > 0$$

Returns to Scale

If we scale all inputs up by some amount $t \geq 0$, what will happen to output?

Constant Returns to Scale

A technology exhibits constant returns to scale if one of the following is satisfied

- i) y is in Y implies ty is in Y , for all $t \geq 0$
- ii) x is in $V(y)$ implies tx is in $V(y)$, for all $t \geq 0$
- iii) $f(tx) = tf(x)$, for all $t \geq 0$, i.e. the production function is homogeneous of degree 1

Increasing Returns to Scale

A technology exhibits increasing returns to scale if $f(tx) > tf(x)$, for all $t > 1$

Decreasing Returns to Scale

A technology exhibits decreasing returns to scale if $f(tx) < tf(x)$, for all $t > 1$

The above measures are global measures. The following gives a local measure of returns to scale

The Elasticity of Scale

The elasticity of scale measures % increase in output due to a one % increase in all inputs

Elasticity of scale $e(x) = \frac{df(tx)}{f(tx)} / \frac{dt}{t}$ evaluated at $t = 1$

or $e(x) = \frac{df(tx)}{dt} \frac{t}{f(tx)}$ evaluated at $t = 1$

The technology exhibits locally IRS if $e(x) > 1$, CRS if $e(x) = 1$, and DRS if $e(x) < 1$.

Monotonic Transformation

A function $g : R \rightarrow R$ is said to be (positive) monotonic transformation if g is a strictly increasing function

If $x > y$ then $g(x) > g(y)$

Homothetic Function

A homothetic function is a monotonic transformation of a homogeneous function (of degree 1)

i.e. $f(x)$ is homothetic iff it can be written as $f(x) = g(h(x))$ where $h(\cdot)$ is homogeneous and $g(\cdot)$ is a monotonic transformation

Homogeneity is a cardinal property whereas Homotheticity is an ordinal property.