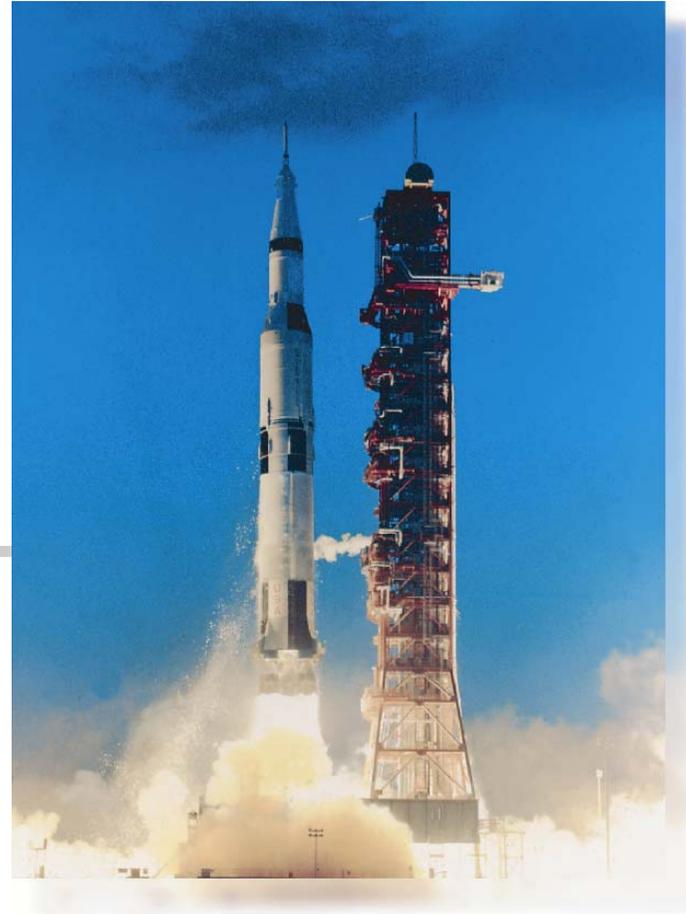


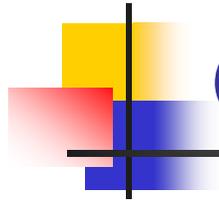
# 0. Introduction

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2142111 Statics, 2011/2

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Engineering, Chulalongkorn University





# Objectives Students must be able to

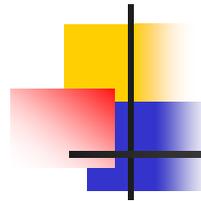
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## Course Objective

- Not specified

## Chapter Objectives

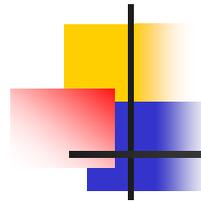
- State the scope of Statics
- Define and identify scalar & vector as well as other type of quantities in mechanics
- State the Newton's laws and Newtonian law of gravitation
- Use appropriate significant figures and unit prefixes
- Describe the procedure of problem solving in Statics



# Contents

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- Basic Concepts
- Scalar and Vector
- Newton's Laws
- Units and Numeral Accuracy
- Analytical Outlines



# Mechanics #1

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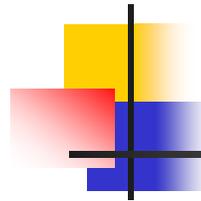
- A branch of physical science that deals with forces and their effects on bodies
- Deal with **force** and **motion**
- First analytical fundamental engineering course

## Statics

Equilibrium of bodies under the action of **forces**

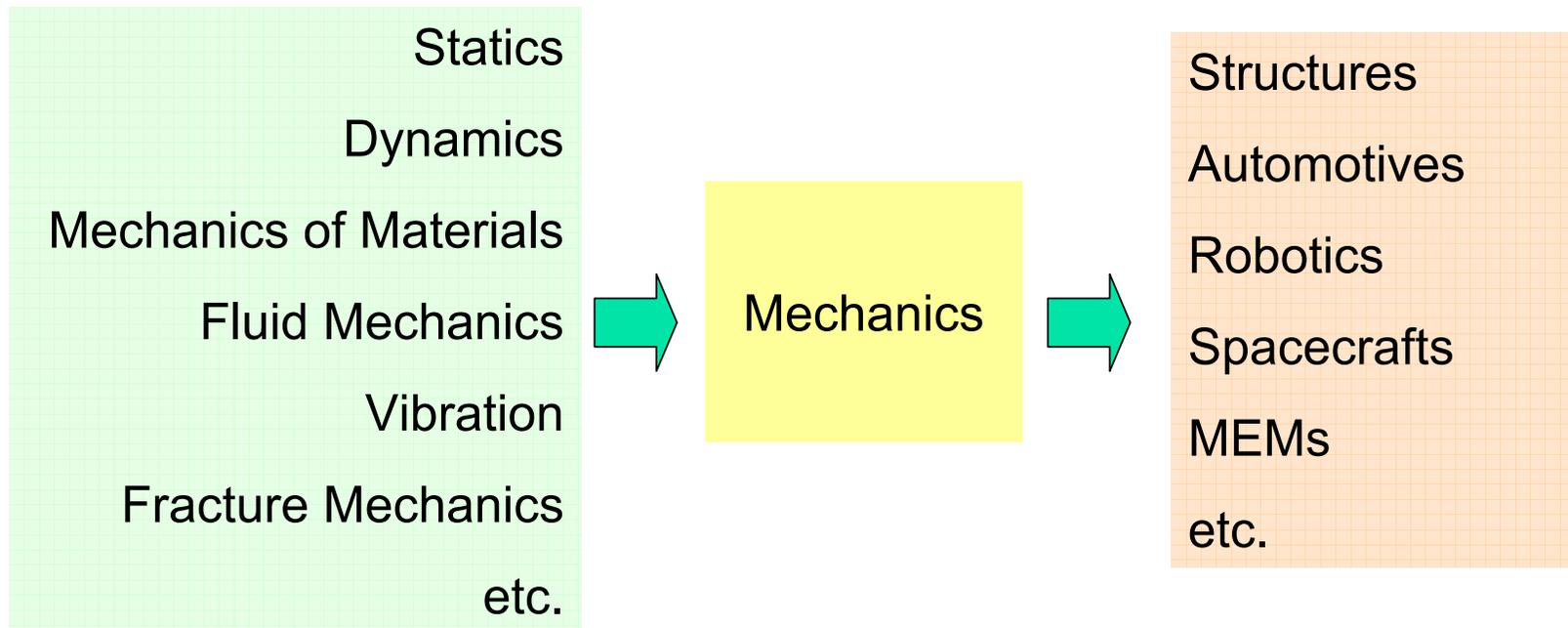
## Dynamics

The **motion** of bodies



# Mechanics #2

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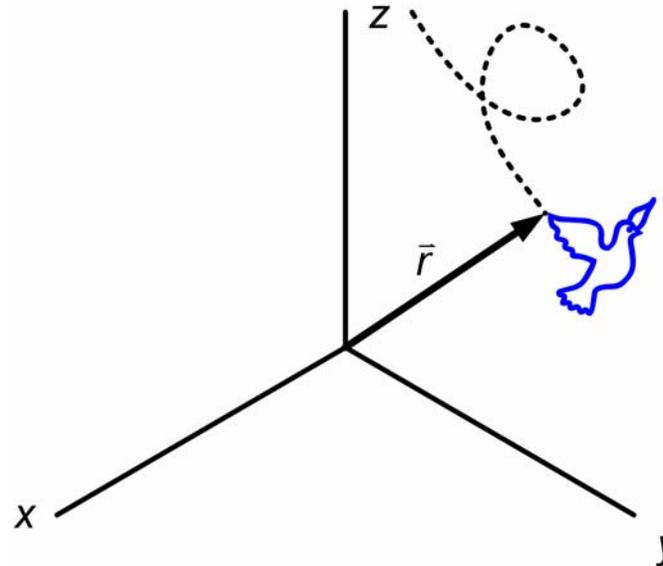
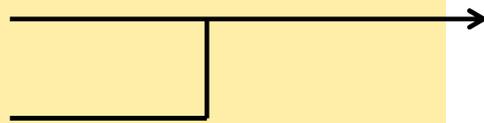
# Basic Definitions

## Body

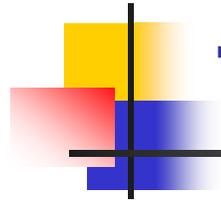
- Particles
- Rigid Bodies
- Deformable Bodies

## Quantity

- Space
- Time
- Force
- Mass



- Position
- Velocity
- Acceleration



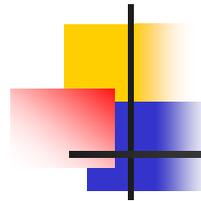
# Tensor Scalar vs. Vector vs. Others

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- Scalar: Magnitude only
  - Exp: mass, length, etc.
  
- Vector: Magnitude + direction
  - Exp: force, position, etc.
  
- Others: Dyads, dyadics, triadics, tetradics, etc.
  - Exp: stress, strain, etc.

# Writing Convention

	Hand	Print
Scalar	$F$	$F$
Vector	$\vec{F}$ $\vec{F}$ $\vec{F}$ $\vec{F}$	$\mathbf{F}$ $\vec{F}$ $\underline{F}$
Unit Vector	$\hat{i}$	$i$ $\hat{i}$
Magnitude of Vector	$F$ $ \vec{F} $	$F$ $ \mathbf{F} $ $ \vec{F} $



# Manipulation

- Scalar: magnitude
- Vector: magnitude & direction, components
  - Scalar multiplication
  - Addition, subtraction
  - Dot product
  - Cross product
  - Mixed triple product

$$a\vec{A}$$

$$\vec{A} + \vec{B}, \vec{A} - \vec{B}$$

$$\vec{A} \cdot \vec{B}$$

$$\vec{A} \times \vec{B}$$

$$\vec{A} \cdot (\vec{B} \times \vec{C})$$

Mathematical Meanings  
vs  
Physical Meanings



# Newton's 1st Law

An object at rest tends to stay at rest and an object in motion tends to stay in motion with the same speed and in the same direction **unless acted upon by an unbalanced force.**



$$\begin{aligned}\sum \vec{F} &= \vec{0} \\ \sum \mathbf{F} &= 0\end{aligned}$$



## Newton's 2nd Law

The acceleration of a particle is proportional to the vector sum of forces acting on it, and is in the direction of this vector sum.



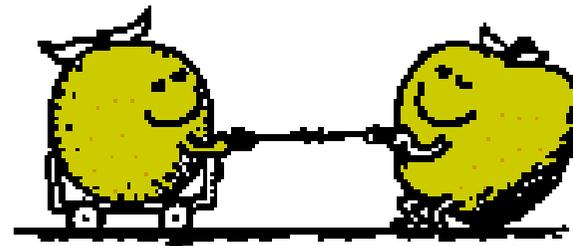
$$\sum \vec{F} = m\vec{a}$$
$$\sum \mathbf{F} = m\mathbf{a}$$



## Newton's 3rd Law

For every action, there is an **equal** and **opposite** reaction.

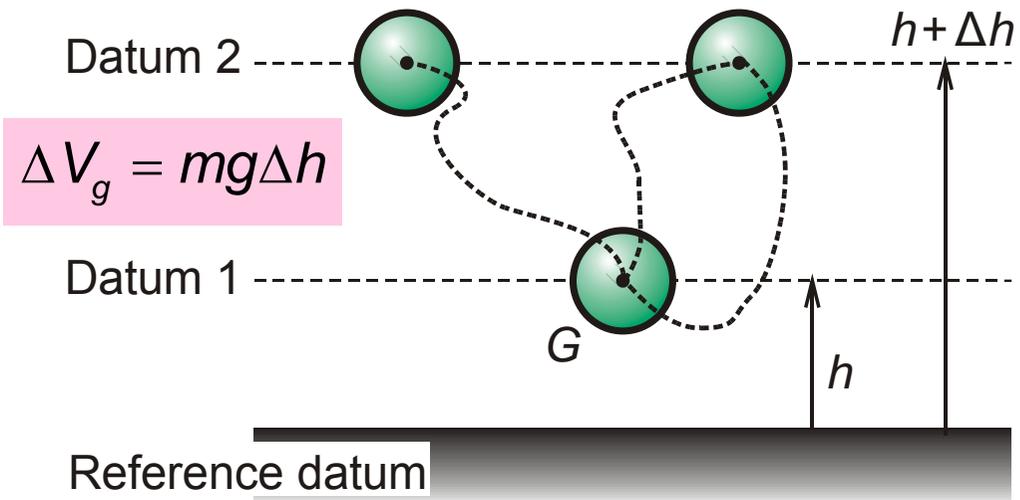
Forces always occur in pairs – equal and opposite action-reaction force pairs.



# Law of Gravitation

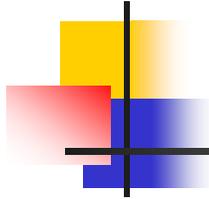
$$F = \frac{Gm_1m_2}{r^2}$$

$F$  = magnitude of gravitational force  
 $G$  = universal gravitational constant  
 $r$  = the distance between particles  
 $m_1, m_2$  = the mass of the two particles



Earth attraction

$$\vec{W} = m\vec{g}$$
$$\mathbf{W} = m\mathbf{g}$$



# Units

- **SI** Units [MLT]  
(International System of Units)
- **U.S. Customary** Units [FPS]  
(British System of Units)

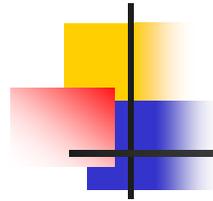
Unit Prefix  
See HW1

Quantity	Unit	Symbol	Dimensional Symbol
Length	meter	m	L
Time	second	s	T
Force	newton	N	F
Mass	kilogram	kg	M

# Accuracy & Approximations

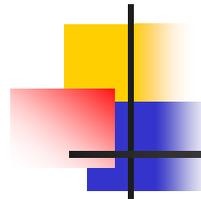
- The number of significant figures (s.f.) in an answer should be no greater than the significant figure numbers of the given data.
- Accuracy to **three significant figures** is considered satisfactory for most engineering results.
  - For instance, you may use 5 s.f. in the calculations and answer with 3 s.f.

$$\begin{aligned}
 1 \text{ kg} \cdot \text{m}^2 / \text{s}^2 &= 1 \text{ kg} \cdot \text{m}^2 / \text{s}^2 \times \left( \frac{1 \text{ slug}}{14.594 \text{ kg}} \right) \times \left( \frac{1 \text{ ft}}{0.3048 \text{ m}} \right)^2 \\
 &= \underline{0.73756} = \underline{0.738 \text{ slug} \cdot \text{ft}^2 / \text{s}^2} \#
 \end{aligned}$$



# Problem Solving Procedure

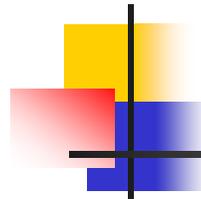
- Formulate problems from physical situations
  - Making appropriate assumptions
- Use graphics
  - The free body diagram or **FBD**
- Apply principles
  - State governing equations
- Substituting variables and calculate numerical values
  - Delay substitute numbers
  - Use appropriate significant figures
- Technical judgment and engineering sense
  - Try to predict the answers
  - Is the answer reasonable?



# Concepts #1

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- Statics is the first course for studying mechanics. The learning is based upon the physics which demands good thinking structures, understanding of physical meanings.
- The basic concepts of Statics involve **space**, **mass** and **force**. Only the **particles** and **rigid bodies** are analysed.
- Main quantity types in Statics are scalar and vector. A **scalar** is associated with the **magnitude** only while a **vector** possesses **magnitude** and **direction**. Basic concepts of scalar and vector were studied in Mathematics but they acquire **physical meanings** here.
- Statics is based on the **Newton's 1st law**, supplemented by the 3rd law and law of gravitation.



## Concepts #2

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- The ***SI units*** are used during study, but US units are also used in real life. The ***significant figure*** indicates the accuracy level of data while the ***prefix*** reduces confusion. Appropriate uses of the significant figure and prefix are necessary.
- Problem solving requires clear problem identification, formulation and solving processes, which must be connected together logically and chronologically. In the solving process, the main components are making assumptions, draw ***FBDs***, stating the ***governing equations, substituting the data*** in FBD into the governing equations, ***solving*** for answers and presenting the solution with ***engineering sense***.