

Multi-variate Statistics

Extension of Bi-variate Statistics

$(Y, X) \sim$ random variables

where

$X \sim$ vectors of K random variables

$$X = [X_1, X_2, \dots, X_K]$$

$Y \sim$ a single random variable

Multi-variate Analyses

- Pair-wise Covariance or Correlation
- Multi-way ANOVA
- Multiple Regression

Multiple Regression Analysis

Focus on the dependency of Y on the X vector, e.g.,

$$\mu_{Y|X} = m(X_1, X_2, \dots, X_K) = m(X)$$

$$\sigma_{Y|X}^2 = v(X_1, X_2, \dots, X_K) = v(X)$$

X_k - explanatory or independent variable,

$$k = 1, \dots, K$$

Y - dependent variable

Multiple Linear Regression

Assumptions

1) linearity $\mu_{Y|X} = X\boldsymbol{\beta}$

where $\boldsymbol{\beta} = [\beta_1 \ \beta_2 \ \dots \ \beta_K]^T$ are
unknown parameters

2) variance-independent or $\sigma_{Y|X}^2 = \sigma^2$

3) normality, i.e. $Y|X \sim N(X\boldsymbol{\beta}, \sigma^2)$

CLNRM (1)

**Classical Linear Normal Regression
Model** is based upon the assumptions

$$Y_i = X_i \beta + \mathcal{E}_i$$

where i = index of the observation

\mathcal{E}_i = identical and independent

normal error term

$$\mathcal{E}_i \sim N(0, \sigma^2) \text{ for all } i=1, \dots, n$$

CLNRM (2)

X_i is pre-selected or non-random but Y_i or
 \mathcal{E}_i is randomly sampled.

$X_i \beta$ is the non-random component of Y_i

\mathcal{E}_i is the random component of Y_i .

Note that X_1 can be intentionally set to
one for all observations so that its
coefficient β_1 becomes the y-intercept.

CLNRM

Matrix Representation (1)

Define

$$\mathbf{Y} = \begin{bmatrix} Y_1 \\ Y_2 \\ \vdots \\ Y_n \end{bmatrix}, \mathbf{X} = \begin{bmatrix} X_{11} & X_{21} & \dots & X_{K1} \\ X_{12} & X_{22} & \dots & X_{K1} \\ \vdots & \vdots & \vdots & \vdots \\ X_{1n} & X_{2n} & \dots & X_{Kn} \end{bmatrix}, \boldsymbol{\varepsilon} = \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \vdots \\ \varepsilon_n \end{bmatrix}$$

CLNRM

Matrix Representation (2)

$$\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\varepsilon}$$

$$\boldsymbol{\varepsilon} \sim MVN\left(\mathbf{0}, \sigma^2 \mathbf{I}_n\right)$$

where

$\mathbf{0}$ is a $n \times 1$ column vector of zeroes

\mathbf{I}_n is an $n \times n$ identity matrix.

CLNRM

Matrix Representation (3)

\mathbf{X} is non-random. It is required that the matrix $\mathbf{X}^T\mathbf{X}$ is invertible. Why?

Remember why we need $\sum_{i=1}^n (X_i - \bar{X})^2 > 0$ in Simple Linear Regression?

OLS Estimation for CLNRM (1)

$$\min_{\boldsymbol{\beta}} \sum_{i=1}^n [Y_i - (X_{1i}\beta_1 + X_{2i}\beta_2 + \dots + X_{Ki}\beta_K)]^2$$

or

$$\min_{\boldsymbol{\beta}} [\mathbf{Y} - \mathbf{X}\boldsymbol{\beta}]^T [\mathbf{Y} - \mathbf{X}\boldsymbol{\beta}]$$

OLS Estimation for CLNRM (2)

First-Order Conditions

$$2[-\mathbf{X}]^T [\mathbf{Y} - \mathbf{X}\boldsymbol{\beta}] = \mathbf{0}$$

$$-\mathbf{X}^T \mathbf{Y} + \mathbf{X}^T \mathbf{X} \boldsymbol{\beta} = \mathbf{0}$$

$$\hat{\boldsymbol{\beta}} = \left[\mathbf{X}^T \mathbf{X} \right]^{-1} \mathbf{X}^T \mathbf{Y}$$

OLS Estimation for CLNRM (3)

Estimator for σ^2

$$\begin{aligned} \hat{\sigma}^2 &= \frac{1}{n-K} \left[\mathbf{Y} - \mathbf{X}\hat{\boldsymbol{\beta}} \right]^T \left[\mathbf{Y} - \mathbf{X}\hat{\boldsymbol{\beta}} \right] \\ &= \frac{1}{n-K} \left[\mathbf{Y}^T \mathbf{Y} - \mathbf{Y}^T \hat{\mathbf{Y}} \right] \end{aligned}$$

where $\hat{\mathbf{Y}} = \mathbf{X}\hat{\boldsymbol{\beta}}$ is called the fitted value of \mathbf{Y}

Why $n-K$?

Properties of OLS estimators (1)

Theorem $E(\hat{\boldsymbol{\beta}}) = \boldsymbol{\beta}$

$$V(\hat{\boldsymbol{\beta}}) = \sigma^2 [\mathbf{X}^T \mathbf{X}]^{-1}$$

Does not require normality assumption.

Note that $\hat{\boldsymbol{\beta}}$ is an unbiased estimator of $\boldsymbol{\beta}$.

Properties of OLS estimators (2)

Proof
$$\begin{aligned} E(\hat{\boldsymbol{\beta}}) &= [\mathbf{X}^T \mathbf{X}]^{-1} \mathbf{X}^T E(\mathbf{Y}) \\ &= [\mathbf{X}^T \mathbf{X}]^{-1} \mathbf{X}^T E(\mathbf{X}\boldsymbol{\beta} + \boldsymbol{\varepsilon}) \\ &= [\mathbf{X}^T \mathbf{X}]^{-1} \mathbf{X}^T [\mathbf{X}\boldsymbol{\beta} + E(\boldsymbol{\varepsilon})] \\ &= [\mathbf{X}^T \mathbf{X}]^{-1} \mathbf{X}^T \mathbf{X}\boldsymbol{\beta} \\ &= \boldsymbol{\beta} \end{aligned}$$

Properties of OLS estimators (3)

Proof

$$\begin{aligned} V(\hat{\boldsymbol{\beta}}) &= [\mathbf{X}^T \mathbf{X}]^{-1} \mathbf{X}^T V(\mathbf{Y}) \left[[\mathbf{X}^T \mathbf{X}]^{-1} \mathbf{X}^T \right]^T \\ &= [\mathbf{X}^T \mathbf{X}]^{-1} \mathbf{X}^T V(\mathbf{Y}) \mathbf{X} [\mathbf{X}^T \mathbf{X}]^{-1} \\ &= [\mathbf{X}^T \mathbf{X}]^{-1} \mathbf{X}^T V(\mathbf{X}\boldsymbol{\beta} + \boldsymbol{\varepsilon}) \mathbf{X} [\mathbf{X}^T \mathbf{X}]^{-1} \\ &= [\mathbf{X}^T \mathbf{X}]^{-1} \mathbf{X}^T V(\boldsymbol{\varepsilon}) \mathbf{X} [\mathbf{X}^T \mathbf{X}]^{-1} \\ &= \sigma^2 [\mathbf{X}^T \mathbf{X}]^{-1} \mathbf{X}^T \mathbf{I}_n \mathbf{X} [\mathbf{X}^T \mathbf{X}]^{-1} \\ &= \sigma^2 [\mathbf{X}^T \mathbf{X}]^{-1} \end{aligned}$$

Properties of OLS estimators (4)

Theorem Due to the normality assumption

of $\boldsymbol{\varepsilon}$,

$$\hat{\boldsymbol{\beta}} \sim MVN\left(\boldsymbol{\beta}, \sigma^2 [\mathbf{X}^T \mathbf{X}]^{-1}\right)$$

and

$$(n - K) \frac{\widehat{\sigma^2}}{\sigma^2} \sim \chi^2(n - K)$$

Properties of OLS estimators (5)

Variance-Covariance Matrix of $\hat{\boldsymbol{\beta}}$

$$V(\hat{\boldsymbol{\beta}}) = \sigma^2 [\mathbf{X}^T \mathbf{X}]^{-1}$$

$$= \begin{bmatrix} V(\hat{\beta}_1) & C(\hat{\beta}_1, \hat{\beta}_2) & \cdots & C(\hat{\beta}_1, \hat{\beta}_K) \\ C(\hat{\beta}_2, \hat{\beta}_1) & V(\hat{\beta}_2) & \cdots & C(\hat{\beta}_2, \hat{\beta}_K) \\ \vdots & \vdots & \ddots & \vdots \\ C(\hat{\beta}_K, \hat{\beta}_1) & C(\hat{\beta}_K, \hat{\beta}_2) & \cdots & V(\hat{\beta}_K) \end{bmatrix}$$

σ^2 is generally unknown.

Properties of OLS estimators (6)

Estimated Variance-Covariance Matrix of $\hat{\boldsymbol{\beta}}$

$$\hat{V}(\hat{\boldsymbol{\beta}}) = \hat{\sigma}^2 (\mathbf{X}^T \mathbf{X})^{-1}$$

$$= \begin{bmatrix} \hat{V}(\hat{\beta}_1) & \hat{C}(\hat{\beta}_1, \hat{\beta}_2) & \cdots & \hat{C}(\hat{\beta}_1, \hat{\beta}_K) \\ \hat{C}(\hat{\beta}_2, \hat{\beta}_1) & \hat{V}(\hat{\beta}_2) & \cdots & \hat{C}(\hat{\beta}_2, \hat{\beta}_K) \\ \vdots & \vdots & \ddots & \vdots \\ \hat{C}(\hat{\beta}_K, \hat{\beta}_1) & \hat{C}(\hat{\beta}_K, \hat{\beta}_2) & \cdots & \hat{V}(\hat{\beta}_K) \end{bmatrix}$$

Properties of OLS estimators (7)

Standard Deviation of $\hat{\beta}_k$

$$sd(\hat{\beta}_k) = \sqrt{V(\hat{\beta}_k)}$$

Standard Error of $\hat{\beta}_k$

$$se(\hat{\beta}_k) = \sqrt{\hat{V}(\hat{\beta}_k)}$$

Properties of OLS estimators (8)

$$\begin{aligned} t_{cal} &= \frac{\hat{\beta}_k - \beta_k}{sd(\hat{\beta}_k)} \\ &= \frac{\hat{\beta}_k - \beta_k}{\sqrt{\frac{(n-K) \frac{\widehat{\sigma}^2}{\sigma^2}}{n-K}}} \\ &= \frac{\hat{\beta}_k - \beta_k}{se(\hat{\beta}_k)} \sim t(n-K) \end{aligned}$$

<<Basis for statistical inference>>

Central Limit Theorem (1)

Similar to that for the Simple Linear Regression Model. Even though the error terms are not normal, the properties of OLS estimators asymptotically hold when the sample size is very large.

Central Limit Theorem (2)

In mathematical term,

$$\sqrt{n}(\hat{\boldsymbol{\beta}} - \boldsymbol{\beta}) \overset{A}{\sim} \text{MVN}\left(\mathbf{0}, \sigma^2 \left[\frac{\mathbf{X}^T \mathbf{X}}{n} \right]^{-1}\right)$$

Gauss-Markov Theorem (1)

Similar to that for the Simple Linear Regression Model. Given that \mathbf{X} is non-random, OLS estimator is Best Linear Unbiased Estimator.

Gauss-Markov Theorem (2)

$\hat{\beta}$ is OLS estimator of β

$\tilde{\beta}$ is a non-OLS linear unbiased estimator of β

$$\mathbf{hV}(\hat{\beta})\mathbf{h}^T \leq \mathbf{hV}(\tilde{\beta})\mathbf{h}^T$$

for any vector $\mathbf{h} \neq \mathbf{0}$

Coefficient of Determination (1)

R^2 is a measure for goodness-of-fit. How well does the model fit the observed data? Low R^2 implies “bad” fit.

Definition
$$R^2 \equiv 1 - \frac{SSR}{SST}$$

SSR = Sum of Squared Residuals

SST = Sum of Squared Totals

Coefficient of Determination (2)

where
$$SSR = \sum_{i=1}^n (Y_i - \hat{Y}_i)^2 = [\mathbf{Y} - \hat{\mathbf{Y}}]^T [\mathbf{Y} - \hat{\mathbf{Y}}]$$

$$SST = \sum_{i=1}^n (Y_i - \bar{Y})^2$$

Note that, in general, R^2 cannot be greater than one but could be negative.

Coefficient of Determination (3)

Low R^2 or a bad fit does not mean a bad model. It simply implies a large uncertainty in the nature. It is mainly used as a criterion to select various “candidate” models.

Coefficient of Determination (4)

If an X_i has constant value or a linear combination of X_i 's is equivalent to a constant value, then, $0 \leq R^2 \leq 1$ always

and

$$R^2 = \frac{\sum_{i=1}^n (\hat{Y}_i - \bar{Y})^2}{\sum_{i=1}^n (Y_i - \bar{Y})^2}$$

Coefficient of Determination (5)

Interpretation if $0 \leq R^2 \leq 1$

$1-R^2$ or SSR/SST can be interpreted as the fraction of total variation of Y due to the random component (\mathcal{E}).

R^2 is generally regarded as the fraction of total variation of Y explained by the explanatory variables or due to the non-random component.

Adjusted- R^2 (1)

We can cheat on R^2 by adding more irrelevant independent variables on the right-hand side, especially when sample is small.

Higher $K \implies$ smaller $SSR \implies$ higher R^2

Adjusted- R^2 (2)

Definition

$$\bar{R}^2 \equiv 1 - \frac{SSR / (n - K)}{SST / (n - 1)} = 1 - \frac{\widehat{\sigma}^2}{s_Y^2}$$

Concept

Penalize R^2 by dividing with $(n-K)$ when an irrelevant variable is added.

Adjusted- R^2 (3)

Purpose

For a small sample, it is a better measure for goodness-of-fit than R^2 . It is also used as criterion to add or remove an explanatory variable from the model if it does not contradict theories.

Statistical Inference about β_k

Confidence Interval for β_k

$$(1-\alpha)100\% \text{ CI for } \beta_k = \hat{\beta}_k \pm t_{\alpha/2}(n-K)se(\hat{\beta}_k)$$

Hypothesis Testing for β_k

$$H_0 : \beta_k = 0.6$$

$$H_1 : \beta_k \neq 0.6 \quad t_{cal} = \frac{\hat{\beta}_k - 0.6}{se(\hat{\beta}_k)}$$

$$|t_{cal}| < t_{\alpha/2}(n-K) \Rightarrow \text{accept } H_0. \text{ Otherwise, reject } H_0.$$

Testing for Effect of X_k on Y

Mean-independence of Y on X_k

$$H_0 : \beta_k = 0$$

$$H_1 : \beta_k \neq 0$$

$$t_{cal} = \frac{\hat{\beta}_k}{se(\hat{\beta}_k)}$$

Accept $H_0 \Rightarrow X_k$ has no significant effect on Y

Overall F-test (1)

Assumption

There is a constant term in the model or X_1 is a vector of one. Why?

Test for mean-independence of Y on $[X_2, X_3, \dots, X_K]$

$$H_0 : \beta_2 = \beta_3 = \dots = \beta_K = 0$$

$$H_1 : \beta_2 \neq \beta_3 \neq \dots \neq \beta_K \neq 0$$

Overall F-test (2)

We are choosing between

$$Y = \beta_1 + \varepsilon \quad \text{---- (H}_0\text{)}$$

expect low R^2 when all X_k 's are included

$$Y = \beta_1 + \beta_2 X_2 + \beta_3 X_3 + \dots + \beta_K X_K + \varepsilon \quad \text{---- (H}_1\text{)}$$

expect higher R^2

Overall F-test (3)

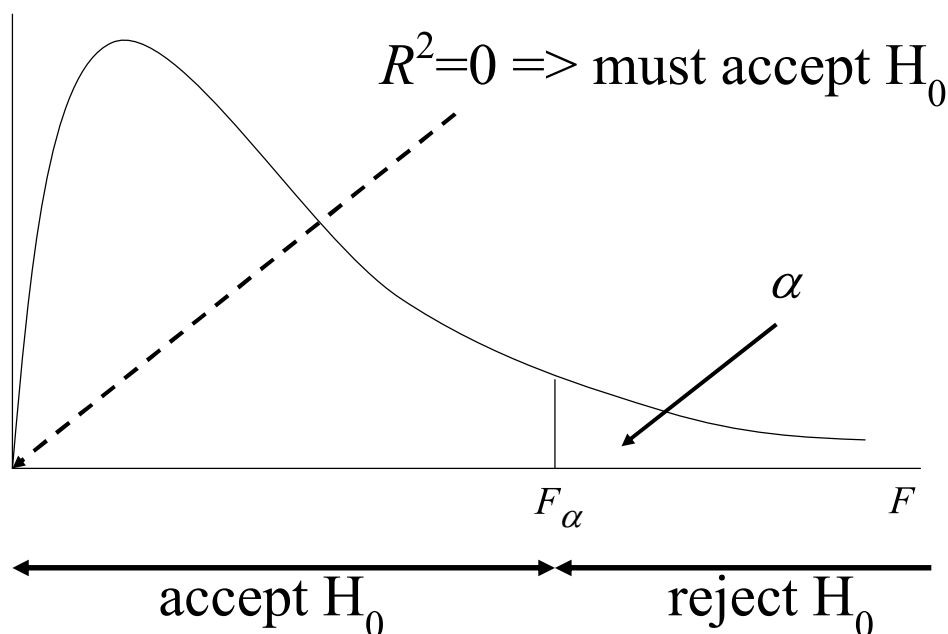
$$F_{cal} = \frac{R^2}{1-R^2} \frac{n-K}{K-1} \sim F(K-1, n-K)$$

Accept H_0 if $F_{cal} < F_{\alpha}(K-1, n-K)$.

Otherwise, reject H_0 . Note that

- 1) an F-test is always right-tailed.
- 2) we need a positive R^2 .

Overall F-test (4)



Generalized F-test (1)

$$H_0 : \mathbf{H}(\boldsymbol{\beta}) = \mathbf{0}$$

$$H_1 : \mathbf{H}(\boldsymbol{\beta}) \neq \mathbf{0}$$

where

$\mathbf{H}(\boldsymbol{\beta})$ is a $M \times 1$ vector function of $\boldsymbol{\beta}$

Note that M must be less than K .

Generalized F-test (2)

$$H_0 : \begin{bmatrix} H_1(\boldsymbol{\beta}) \\ H_2(\boldsymbol{\beta}) \\ \vdots \\ H_M(\boldsymbol{\beta}) \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix} \quad H_1 : \begin{bmatrix} H_1(\boldsymbol{\beta}) \\ H_2(\boldsymbol{\beta}) \\ \vdots \\ H_M(\boldsymbol{\beta}) \end{bmatrix} \neq \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

or

$$H_0 : H_1(\boldsymbol{\beta}) = 0, H_2(\boldsymbol{\beta}) = 0, \dots, H_M(\boldsymbol{\beta}) = 0$$

$$H_1 : H_1(\boldsymbol{\beta}) \neq 0, H_2(\boldsymbol{\beta}) \neq 0, \dots, H_M(\boldsymbol{\beta}) \neq 0$$

Generalized F-test (3)

Linear Restriction

$\mathbf{H}(\boldsymbol{\beta})$ is a $M \times 1$ vector linear function of $\boldsymbol{\beta}$

$$\mathbf{H}(\boldsymbol{\beta}) = \mathbf{R}\boldsymbol{\beta} - \mathbf{r}$$

where \mathbf{R} is an $M \times K$ coefficient matrix with

$$\text{Rank} = M$$

\mathbf{r} is a $M \times 1$ constant vector

$$H_0 : \mathbf{R}\boldsymbol{\beta} - \mathbf{r} = \mathbf{0} \text{ or } \mathbf{R}\boldsymbol{\beta} = \mathbf{r}$$

$$H_1 : \mathbf{R}\boldsymbol{\beta} - \mathbf{r} \neq \mathbf{0} \text{ or } \mathbf{R}\boldsymbol{\beta} \neq \mathbf{r}$$

Generalized F-test (4)

Two approaches

- Restricted Least Square (RLS)
- Wald Test

Restricted Least Square (1)

Require two LS runs

Unrestricted run is the OLS run on the original model

$$\implies SSR_U$$

where

SSR_U is the sum of squared residuals from the unrestricted run

Restricted Least Square (2)

Restricted LS run is as follows

$$\min_{\beta} [Y - X\beta]^T [Y - X\beta]$$

$$\text{subject to } \mathbf{R}\beta = \mathbf{r}$$

$$\implies SSR_R$$

where

SSR_R is the sum of squared residuals from the restricted run

Restricted Least Square (3)

Transform RLS to OLS (Elimination Approach)

Define $\mathbf{R} = [\mathbf{A} \mathbf{B}]$ where

\mathbf{A} is an $M \times M$ invertible sub-matrix of \mathbf{R}

\mathbf{B} is the $M \times (K-M)$ sub-matrix containing columns of \mathbf{R} not in \mathbf{A}

Restricted Least Square (4)

Define $\mathbf{X} = [\mathbf{V} \mathbf{W}]$ where

\mathbf{V} is an $N \times M$ sub-matrix of \mathbf{X}

\mathbf{W} is the $N \times (K-M)$ sub-matrix containing columns of \mathbf{X} not in \mathbf{V}

Restricted Least Square (5)

Re-write the restriction as

$$\begin{bmatrix} \mathbf{A} & \mathbf{B} \end{bmatrix} \begin{bmatrix} \boldsymbol{\gamma} \\ \boldsymbol{\delta} \end{bmatrix} = \mathbf{r} \quad \text{or} \quad \mathbf{A}\boldsymbol{\gamma} + \mathbf{B}\boldsymbol{\delta} = \mathbf{r}$$

where

$\boldsymbol{\gamma}$ is a $M \times 1$ subset of $\boldsymbol{\beta}$

$\boldsymbol{\delta}$ is a $(K-M) \times 1$ subset of $\boldsymbol{\beta}$

Restricted Least Square (6)

Re-write the model as

$$\begin{aligned} \mathbf{Y} &= \begin{bmatrix} \mathbf{V} & \mathbf{W} \end{bmatrix} \begin{bmatrix} \boldsymbol{\gamma} \\ \boldsymbol{\delta} \end{bmatrix} + \boldsymbol{\varepsilon} \\ &= \mathbf{V}\boldsymbol{\gamma} + \mathbf{W}\boldsymbol{\delta} + \boldsymbol{\varepsilon} \end{aligned}$$

Restricted Least Square (7)

Since \mathbf{A} is invertible,

$$\boldsymbol{\gamma} = \mathbf{A}^{-1}[\mathbf{r} - \mathbf{B}\boldsymbol{\delta}]$$

Substitute into the model.

$$\mathbf{Y} = \mathbf{V}\mathbf{A}^{-1}[\mathbf{r} - \mathbf{B}\boldsymbol{\delta}] + \mathbf{W}\boldsymbol{\delta} + \boldsymbol{\varepsilon}$$

$$\mathbf{Y} - \mathbf{V}\mathbf{A}^{-1}\mathbf{r} = [\mathbf{W} - \mathbf{V}\mathbf{A}^{-1}\mathbf{B}]\boldsymbol{\delta} + \boldsymbol{\varepsilon}$$

Restricted Least Square (8)

$$\mathbf{P} = \mathbf{Z}\boldsymbol{\delta} + \boldsymbol{\varepsilon}$$

where $\mathbf{P} = \mathbf{Y} - \mathbf{V}\mathbf{A}^{-1}\mathbf{r}$, $\mathbf{Z} = \mathbf{W} - \mathbf{V}\mathbf{A}^{-1}\mathbf{B}$

Apply OLS

$$\hat{\boldsymbol{\delta}} = [\mathbf{Z}^T\mathbf{Z}]^{-1}\mathbf{Z}^T\mathbf{P}$$

$$\hat{\boldsymbol{\gamma}} = \mathbf{A}^{-1}[\mathbf{r} - \mathbf{B}\hat{\boldsymbol{\delta}}]$$

$$\hat{\sigma}_R^2 = \frac{SSR_R}{n - (K - M)} \quad SSR_R = [\mathbf{P} - \mathbf{Z}\hat{\boldsymbol{\delta}}]^T[\mathbf{P} - \mathbf{Z}\hat{\boldsymbol{\delta}}]$$

Restricted Least Square (9)

$$V(\hat{\delta}) = \sigma^2 [\mathbf{Z}^T \mathbf{Z}]^{-1}$$

$$\begin{aligned} V(\hat{\gamma}) &= \mathbf{A}^{-1} \mathbf{B} V(\hat{\delta}) \mathbf{B}^T [\mathbf{A}^T]^{-1} \\ &= \sigma^2 \mathbf{A}^{-1} \mathbf{B} [\mathbf{Z}^T \mathbf{Z}]^{-1} \mathbf{B}^T [\mathbf{A}^T]^{-1} \end{aligned}$$

$$\text{COV}(\hat{\gamma}, \hat{\delta}) = \sigma^2 \mathbf{A}^{-1} \mathbf{B} [\mathbf{Z}^T \mathbf{Z}]^{-1}$$

$$V(\hat{\beta}_R) = \sigma^2 \begin{bmatrix} \mathbf{A}^{-1} \mathbf{B} [\mathbf{Z}^T \mathbf{Z}]^{-1} \mathbf{B}^T [\mathbf{A}^T]^{-1} & \mathbf{A}^{-1} \mathbf{B} [\mathbf{Z}^T \mathbf{Z}]^{-1} \\ [\mathbf{Z}^T \mathbf{Z}]^{-1} \mathbf{B}^T [\mathbf{A}^T]^{-1} & [\mathbf{Z}^T \mathbf{Z}]^{-1} \end{bmatrix}$$

Restricted Least Square (10)

Lagrange Method

$$\text{FOC} \quad -\mathbf{X}^T [\mathbf{Y} - \mathbf{X}\beta] + \mathbf{R}^T \hat{\lambda} = \mathbf{0}$$

$$\mathbf{X}^T \mathbf{Y} - \mathbf{X}^T \mathbf{X} \hat{\beta}_R - \mathbf{R}^T \hat{\lambda} = \mathbf{0}$$

$$\begin{aligned} \hat{\beta}_R &= [\mathbf{X}^T \mathbf{X}]^{-1} [\mathbf{X}^T \mathbf{Y} - \mathbf{R}^T \hat{\lambda}] \\ &= [\mathbf{X}^T \mathbf{X}]^{-1} \mathbf{X}^T \mathbf{Y} - [\mathbf{X}^T \mathbf{X}]^{-1} \mathbf{R}^T \hat{\lambda} \\ &= \hat{\beta}_U - [\mathbf{X}^T \mathbf{X}]^{-1} \mathbf{R}^T \hat{\lambda} \end{aligned}$$

Restricted Least Square (11)

Substitute into $\mathbf{R}\hat{\boldsymbol{\beta}} = \mathbf{r}$

$$\begin{aligned} [\mathbf{R}\hat{\boldsymbol{\beta}}_U - \mathbf{r}] - \mathbf{R}[\mathbf{X}^T \mathbf{X}]^{-1} \mathbf{R}^T \hat{\boldsymbol{\lambda}} &= \mathbf{0} \\ \hat{\boldsymbol{\lambda}} &= \mathbf{S}^{-1} [\mathbf{R}\hat{\boldsymbol{\beta}}_U - \mathbf{r}] \end{aligned}$$

where $\mathbf{S} = \mathbf{R}[\mathbf{X}^T \mathbf{X}]^{-1} \mathbf{R}^T$

$$\begin{aligned} \hat{\boldsymbol{\beta}}_R &= \hat{\boldsymbol{\beta}}_U - [\mathbf{X}^T \mathbf{X}]^{-1} \mathbf{R}^T \mathbf{S}^{-1} [\mathbf{R}\hat{\boldsymbol{\beta}}_U - \mathbf{r}] \\ &= [\mathbf{I} - [\mathbf{X}^T \mathbf{X}]^{-1} \mathbf{R}^T \mathbf{S}^{-1} \mathbf{R}] \hat{\boldsymbol{\beta}}_U \\ &\quad + [\mathbf{X}^T \mathbf{X}]^{-1} \mathbf{R}^T \mathbf{S}^{-1} \mathbf{r} \end{aligned}$$

Restricted Least Square (12)

$$V(\hat{\boldsymbol{\beta}}_R) = \sigma^2 \mathbf{D}[\mathbf{X}^T \mathbf{X}]^{-1} \mathbf{D}^T$$

where $\mathbf{D} = \mathbf{I} - [\mathbf{X}^T \mathbf{X}]^{-1} \mathbf{R}^T \mathbf{S}^{-1} \mathbf{R}$

$$\hat{\sigma}_R^2 = \frac{SSR_R}{n - (K - M)}$$

where $SSR_R = [\mathbf{Y} - \mathbf{X}\hat{\boldsymbol{\beta}}_R]^T [\mathbf{Y} - \mathbf{X}\hat{\boldsymbol{\beta}}_R]$

Prove that both RLS and LM yield identical result

Restricted Least Square (13)

$$F_{cal} = \frac{(SSR_R - SSR_U)/M}{SSR_U/(n-K)} \sim F(M, n-K)$$

where

M is the number of restriction equations or constraints or the number of rows in matrix \mathbf{R}

Note that $df_U = n-K$ and $df_R = n-(K-M)$

Restricted Least Square (14)

$$F_{cal} < F_{\alpha}(M, n-K) \implies \text{Accept } H_0$$

or restriction holds

$$F_{cal} > F_{\alpha}(M, n-K) \implies \text{Reject } H_0 \text{ or restriction}$$

does not holds

Wald Test (1)

Require only the Unrestricted run

$$\implies \hat{\boldsymbol{\beta}}, \hat{\sigma}^2$$

$$F_{cal} = [\mathbf{R}\hat{\boldsymbol{\beta}} - \mathbf{r}]^T [\mathbf{R}[\mathbf{X}^T \mathbf{X}]^{-1} \mathbf{R}^T]^{-1} [\mathbf{R}\hat{\boldsymbol{\beta}} - \mathbf{r}] \frac{1}{\hat{\sigma}^2 M}$$

$$\sim F(M, n - K)$$

Accept H_0 if $F_{cal} < F_{\alpha}(M, n - K)$.

Otherwise, reject H_0 .

Wald Test (2)

Concept

Note that, given H_0 is true,

$$[\mathbf{R}\hat{\boldsymbol{\beta}} - \mathbf{r}] \sim \text{MVN}(\mathbf{0}, \sigma^2 \mathbf{R}[\mathbf{X}^T \mathbf{X}]^{-1} \mathbf{R}^T)$$

Standardize a normal vector

$$\mathbf{Z} = \left[\sigma^2 \mathbf{R}[\mathbf{X}^T \mathbf{X}]^{-1} \mathbf{R}^T \right]^{-\frac{1}{2}} [\mathbf{R}\hat{\boldsymbol{\beta}} - \mathbf{r}]$$

Wald Test (3)

Note that \mathbf{Z} is a vector of M iid standard normal RV's

$$\begin{aligned}\mathbf{Z}^T \mathbf{Z} &= [\mathbf{R}\hat{\boldsymbol{\beta}} - \mathbf{r}]^T \left[\sigma^2 \mathbf{R}[\mathbf{X}^T \mathbf{X}]^{-1} \mathbf{R}^T \right]^{-1} [\mathbf{R}\hat{\boldsymbol{\beta}} - \mathbf{r}] \\ &\sim \chi^2(M)\end{aligned}$$

Wald Test (4)

$$\begin{aligned}F_{cal} &= \frac{\frac{\mathbf{Z}^T \mathbf{Z}}{M}}{\frac{(n-K) \frac{\hat{\sigma}^2}{\sigma^2}}{n-K}} \sim F(M, n-K) \\ &= [\mathbf{R}\hat{\boldsymbol{\beta}} - \mathbf{r}]^T \left[\mathbf{R}[\mathbf{X}^T \mathbf{X}]^{-1} \mathbf{R}^T \right]^{-1} [\mathbf{R}\hat{\boldsymbol{\beta}} - \mathbf{r}] \frac{1}{\hat{\sigma}^2 M}\end{aligned}$$

Example#1 (1)

Overall F-test is a simple case of
Generalized F-tests with

$$\mathbf{R}_{(K-1) \times K} = \begin{bmatrix} 0 & 1 & 0 & \cdots & 0 \\ 0 & 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & 1 \end{bmatrix}, \mathbf{r} = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

Example#1 (2)

RLS Approach

Since the restriction set is simple, the
restricted model can be written as

$$Y_i = \beta_1 + \varepsilon_i$$

By OLS $\Rightarrow \hat{\beta}_1 = \bar{Y}$

$$SSR_R = \sum_{i=1}^n (Y_i - \hat{\beta}_1)^2 = \sum_{i=1}^n (Y_i - \bar{Y})^2$$

Example#1 (3)

Note that $SSR_R = SST$ of the unrestricted model.

$$\begin{aligned} F_{cal} &= \frac{SST_U - SSR_U}{SSR_U} \frac{n - K}{K - 1} \\ &= \frac{(SST_U - SSR_U) / SST_U}{SSR_U / SST_U} \frac{n - K}{K - 1} \\ &= \frac{R^2}{1 - R^2} \frac{n - K}{K - 1} \end{aligned}$$

Example#1 (4)

Wald Test (single-run)

See Eviews example

Example#2 (1)

Removing X_2 and X_3

$$H_0 : \beta_2 = 0, \beta_3 = 0$$

$$H_1 : \beta_2 \neq 0, \beta_3 \neq 0$$

Use this \mathbf{R} and \mathbf{r} in the test

$$\mathbf{R}_{2 \times K} = \begin{bmatrix} 0 & 1 & 0 & 0 & \cdots & 0 \\ 0 & 0 & 1 & 0 & \cdots & 0 \end{bmatrix}, \mathbf{r} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Example#2 (2)

RLS Approach

Since the restriction set is simple, the restricted model can be written as

$$Y_i = \beta_1 + \beta_4 X_{4i} + \cdots + \beta_K X_{Ki} + \varepsilon_i$$

Example#3 (1)

$$H_0 : \beta_2 = 0, \beta_3 = 0, \beta_4 + \beta_5 = 1$$

$$H_1 : \beta_2 \neq 0, \beta_3 \neq 0, \beta_4 + \beta_5 \neq 1$$

Use this \mathbf{R} and \mathbf{r} in the test

$$\mathbf{R} = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 0 & \dots & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & \dots & 0 \\ 0 & 0 & 0 & 1 & 1 & 0 & \dots & 0 \end{bmatrix}, \mathbf{r} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

Example#3 (2)

RLS Approach

Since the restriction set is simple, the restricted model can be written as

$$Y_i = \beta_1 + \beta_4 X_{4i} + (1 - \beta_4) X_{5i} + \dots + \beta_K X_{Ki} + \varepsilon_i$$

$$Y_i - X_{5i} = \beta_1 + \beta_4 (X_{4i} - X_{5i}) + \beta_6 X_{6i} + \dots + \beta_K X_{Ki} + \varepsilon_i$$

Normality Tests

- Cumulative Normal plot
- Goodness-of-fit test (a Chi-square test)
- Jarque-Bera Test

Cumulative Normal Plot (1)

If X is normal, graph of inverse CDF of cumulative relative frequency versus X will exhibit linearity

Step 1 Sort X

Step 2 Calculate Cumulative Relative frequency F for each X . Note that

$$0 < F < 1$$

Cumulative Normal Plot (2)

Step 3 Calculate (look for in the Z-table) the Z value for the area on left equal to F

Step 4 Plot Z against standardized X

If the graph is linear with slope of +1, $\implies X \sim \text{Normal}$

Jarque-Bera Normality Test (1)

$$H_0 : S = 0, \kappa = 3$$

$$H_1 : S \neq 0, \kappa \neq 3$$

where S is skewedness

\mathbf{K} is Kurtosis

$$\chi_{cal}^2 = (n - K) \left(\frac{1}{6} \hat{S}^2 + \frac{1}{24} (\hat{\kappa} - 3)^2 \right) \sim \chi_{\alpha}^2(2)$$

Jarque-Bera Normality Test (2)

where
$$\hat{\sigma} = \sqrt{\frac{1}{n-1} \sum_{i=1}^n (X_i - \bar{X})^2}$$

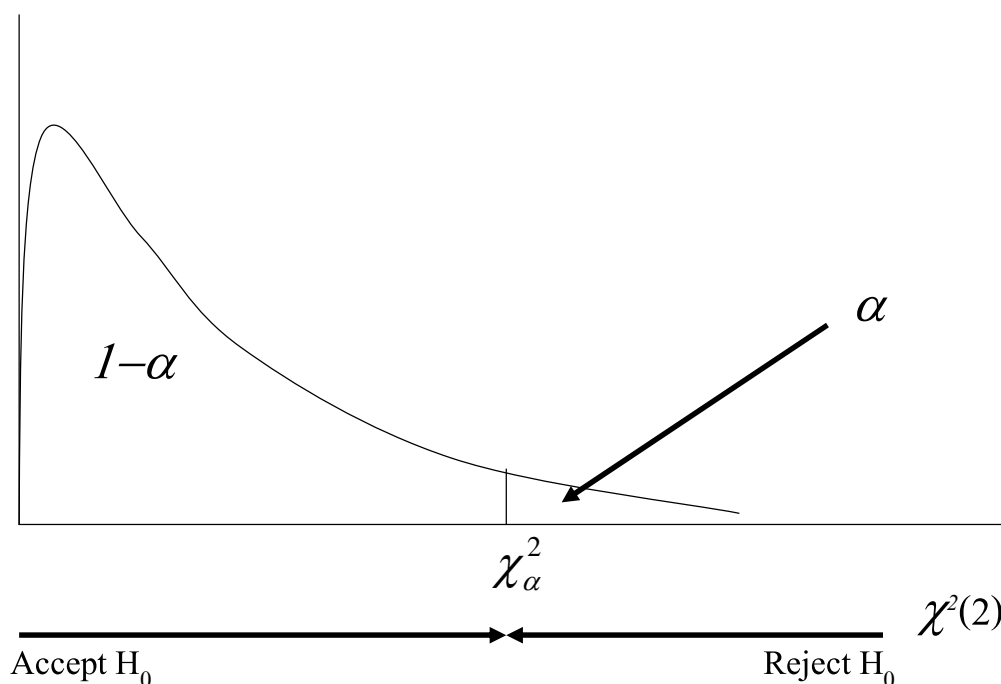
$$\hat{S} = \frac{1}{n} \sum_{i=1}^n \left(\frac{X_i - \bar{X}}{\hat{\sigma}} \right)^3$$

$$\hat{K} = \frac{1}{n} \sum_{i=1}^n \left(\frac{X_i - \bar{X}}{\hat{\sigma}} \right)^4$$

Perform a right-tailed χ^2 -test

Note: different definition for skewedness and kurtosis

Jarque-Bera Normality Test (3)



Prediction Interval of Y (1)

$$E(Y | \mathbf{X}_0) = \mathbf{X}_0 \boldsymbol{\beta}$$

$$\widehat{E(Y | \mathbf{X}_0)} = \mathbf{X}_0 \hat{\boldsymbol{\beta}}$$

Is an unbiased estimator of $E(Y|\mathbf{X}_0)$

where $\mathbf{X}_0 = [X_{10}, X_{20}, \dots, X_{K0}]$

$$\begin{aligned} V(\widehat{E(Y | \mathbf{X}_0)}) &= \mathbf{X}_0 \mathbf{V}(\hat{\boldsymbol{\beta}}) [\mathbf{X}_0]^\top \\ &= \sigma^2 \mathbf{X}_0 [\mathbf{X}^\top \mathbf{X}]^{-1} [\mathbf{X}_0]^\top \end{aligned}$$

Prediction Interval of Y (2)

$(1-\alpha)100\%$ CI for $E(Y|\mathbf{X}_0) =$

$$= \mathbf{X}_0 \hat{\boldsymbol{\beta}} + t_{\frac{\alpha}{2}}(n-K) \text{se}(\widehat{E(Y | \mathbf{X}_0)})$$

where

$$\text{se}(\widehat{E(Y | \mathbf{X}_0)}) = \sqrt{\sigma^2 \mathbf{X}_0 [\mathbf{X}^\top \mathbf{X}]^{-1} [\mathbf{X}_0]^\top}$$

Prediction Interval of Y (3)

$(1-\alpha)100\%$ PI for $Y|\mathbf{X}_0 =$

$$= \mathbf{X}_0 \hat{\boldsymbol{\beta}} + t_{\frac{\alpha}{2}} (n - K) \text{se}(Y | \mathbf{X}_0)$$

where

$$\text{se}(Y | \mathbf{X}_0) = \sqrt{\hat{\sigma}^2 \left(1 + \mathbf{X}_0 [\mathbf{X}^T \mathbf{X}]^{-1} [\mathbf{X}_0]^T \right)}$$