

Unit Root Tests

Test for Stationarity

- Correlogram (Graphical)
- Unit Root Tests
 - Dickey-Fuller
 - Phillip-Perron

Dickey-Fuller's UR Test (1)

Assumptions

$$Y_t \sim \text{AR}(1)$$

Hypothesis

$$H_0: Y_t \sim \text{non-stationary}$$

$$H_1: Y_t \sim \text{stationary}$$

Dickey-Fuller's UR Test(2)

CASE I

$$Y_t \sim \text{AR}(1) \text{ w/o drift and trend}$$

Testing Model

$$Y_t = \phi_1 Y_{t-1} + \varepsilon_t$$

Dickey-Fuller's UR Test(3)

Testing Model

$$Y_t - Y_{t-1} = (\phi_1 - 1)Y_{t-1} + \varepsilon_t$$

$$\Delta Y_t = \gamma_1 Y_{t-1} + \varepsilon_t$$

where $\gamma = \phi_1 - 1$

$$H_0: \phi_1 \geq 1 \text{ or } \gamma \geq 0$$

$$H_1: \phi_1 < 1 \text{ or } \gamma < 0 \leftarrow \text{Necessary condition}$$

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Dickey-Fuller's UR Test(4)

Steps

1) run OLS of ΔY_t on Y_{t-1}

2) test for $\gamma < 0$

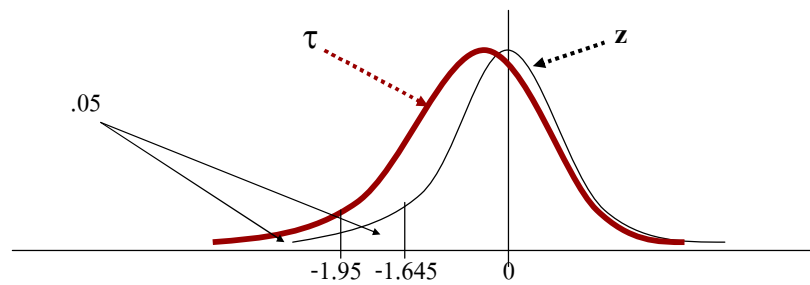
$$\tau = \frac{\hat{\gamma}}{se(\hat{\gamma})} \sim ??$$

DF have shown by simulation that τ does not follow a t -dist or a normal

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Dickey-Fuller's UR Test(5)



Ref: Table 4.1 page 223 (Enders), Table D.7 (Gujarati)

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Dickey-Fuller's UR Test(6)

CASE II

$Y_t \sim \text{AR}(1)$ w/ drift but w/o trend

Testing Model

$$Y_t = a_0 + \phi_1 Y_{t-1} + \varepsilon_t$$

$$\Delta Y_t = a_0 + \gamma_1 Y_{t-1} + \varepsilon_t$$

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Dickey-Fuller's UR Test(7)

Steps

1) run OLS of ΔY_t on constant Y_{t-1}

2) test for $\gamma < 0$

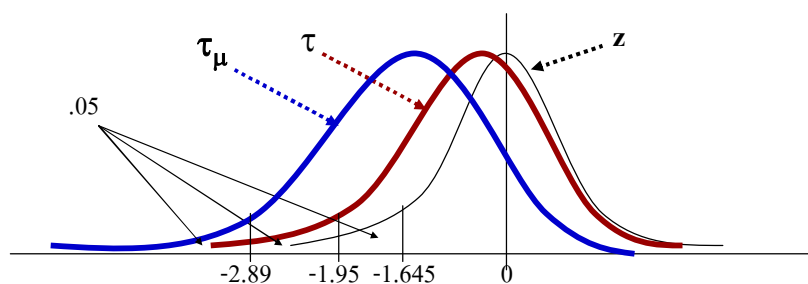
$$\tau_{\mu} = \frac{\hat{\gamma}}{se(\hat{\gamma})} \sim ??$$

DF have shown by simulation that τ_{μ} does not follow a t -dist or a normal

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Dickey-Fuller's UR Test(8)



Ref: Table 4.1 page 223

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Dickey-Fuller's UR Test(9)

CASE III

$Y_t \sim \text{AR}(1)$ w/ drift and trend

Testing Model

$$Y_t = a_0 + \phi_1 Y_{t-1} + a_2 t + \varepsilon_t$$

$$\Delta Y_t = a_0 + \gamma_1 Y_{t-1} + a_2 t + \varepsilon_t$$

Dickey-Fuller's UR Test(10)

Steps

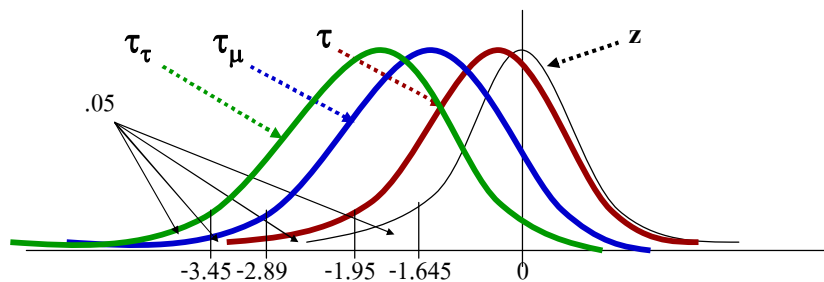
1) run OLS of ΔY_t on constant t Y_{t-1}

2) test for $\gamma < 0$

$$\tau_\tau = \frac{\hat{\gamma}}{se(\hat{\gamma})} \sim ??$$

DF have shown by simulation that τ_τ does not follow a t -dist or a normal

Dickey-Fuller's UR Test(11)



Ref: Table 4.1 page 223

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Dickey-Fuller's UR Test(12)

Note that

Drift and time trend will make it
more difficult to reject H_0 .

If H_0 is rejected when both are
included, it will be rejected in the
other cases.

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Dickey-Fuller's UR Test(12)

Simple Rule

First, include both drift and trend in the testing model. Do τ_{τ} test.

If reject, $Y \sim$ stationary

Otherwise, remove trend and do τ_{μ} test.

If reject, $Y \sim$ stationary. Otherwise, remove drift and do τ test.

If reject, $Y \sim$ stationary. Otherwise, Y is non-stationary

Dickey-Fuller's UR Test(12)

Full-scheme testing rule

See Figure 4.7 on page 257

Augmented Dickey-Fuller (1)

Assumptions

$$Y_t \sim \text{AR}(p)$$

Testing Model

$$Y_t = \phi_1 Y_{t-1} + \phi_2 Y_{t-2} + \cdots + \phi_{p-1} Y_{t-p+1} \\ + \phi_p Y_{t-p+1} - \phi_p (Y_{t-p+1} - Y_{t-p}) + \varepsilon_t$$

Augmented Dickey-Fuller (2)

$$Y_t = \phi_1 Y_{t-1} + \phi_2 Y_{t-2} + \cdots + (\phi_{p-1} + \phi_p) Y_{t-p+2} \\ + (-\phi_{p-1} - \phi_p) (Y_{t-p+2} - Y_{t-p+1}) \\ + (-\phi_p) \Delta Y_{t-p+1} + \varepsilon_t \\ = \phi_1 Y_{t-1} + \phi_2 Y_{t-2} + \cdots + (\phi_{p-1} + \phi_p) Y_{t-p+2} \\ + (-\phi_{p-1} - \phi_p) \Delta Y_{t-p+2} + (-\phi_p) \Delta Y_{t-p+1} + \varepsilon_t \\ \vdots$$

Augmented Dickey-Fuller (3)

$$\begin{aligned}\Delta Y_t &= (\phi_1 + \phi_2 + \phi_2 + \dots + \phi_p - 1)Y_{t-1} \\ &+ (-\phi_2 - \phi_2 - \dots - \phi_p)\Delta Y_{t-1} + \dots \\ &+ (-\phi_{p-2} - \phi_{p-1} - \phi_p)\Delta Y_{t-p+3} \\ &+ (-\phi_{p-1} - \phi_p)\Delta Y_{t-p+2} \\ &+ (-\phi_p)\Delta Y_{t-p+1} + \varepsilon_t\end{aligned}$$

p-1 Augmented terms

Augmented Dickey-Fuller (4)

Hypothesis

$$H_0: \gamma \geq 0$$

$$H_1: \gamma < 0$$

where $\gamma = \phi_1 + \phi_2 + \phi_2 + \dots + \phi_p - 1$
Fortunately, we can use the same τ_τ ,
 τ_μ and τ tests as DF unit root tests