

# Engineering Mechanics 1

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# 1/1 Mechanics

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**Mechanics** is the physical science which deals with the effects of forces on objects

The subject of mechanics is divided into two parts:

1. **Statics:** equilibrium of bodies
2. **Dynamics:** motion of bodies

## **Applications**

- Strength of machines and structures
- Vibrations (engine, building, bridge)
- Fluid mechanics (airplanes, fluid machinery)

# 1/2 Basic concepts

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- Space:** the region occupied by bodies whose positions are described using coordinate system (meter)
- Time:** the measure of the succession of events (sec)  
Used in dynamics
- Mass:** the body's resistance to change in velocity (kg)  
the body's ability to generate attractive force between itself and another
- Force:** the action of one body to another (N)
- Particle:** a body of negligible dimensions (dimensions are not significant to the description of its position or forces applied to it) → concentrated mass
- Rigid body:** a body with negligible deformation

# 1/3 Scalars and vectors

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**Scalars:** only *magnitude* is associated

Ex. mass, volume, density, speed, length, angle

**Vectors:** *magnitude* and *direction* are important

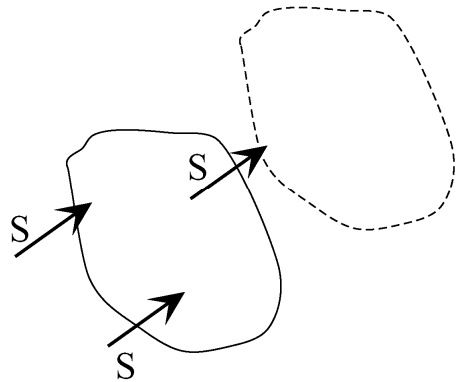
Ex. Displacement, velocity, acceleration, force, moment

Vectors can be classified by the importance of their position

1. Free vector
2. Sliding vector
3. Fixed vector

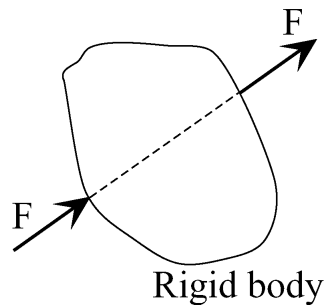
# 1/3 Scalars and vectors

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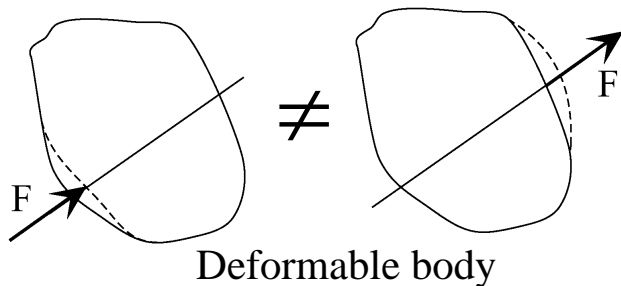
## Free vector

Displacement of body moving without rotation



## Sliding vector

Force acting on a rigid body

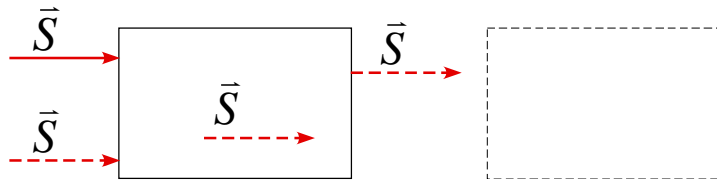


## Fixed vector

The action of force on a deformable body

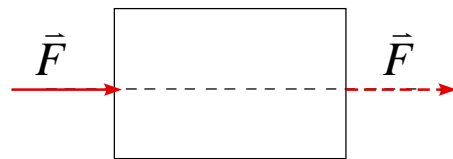
# 1/3 Scalars and vectors

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## Free vector

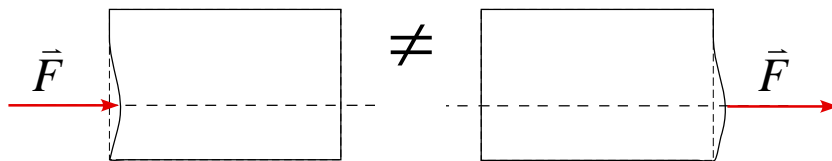
Displacement of body moving without rotation



Rigid body

## Sliding vector

Force acting on a rigid body



Deformable body

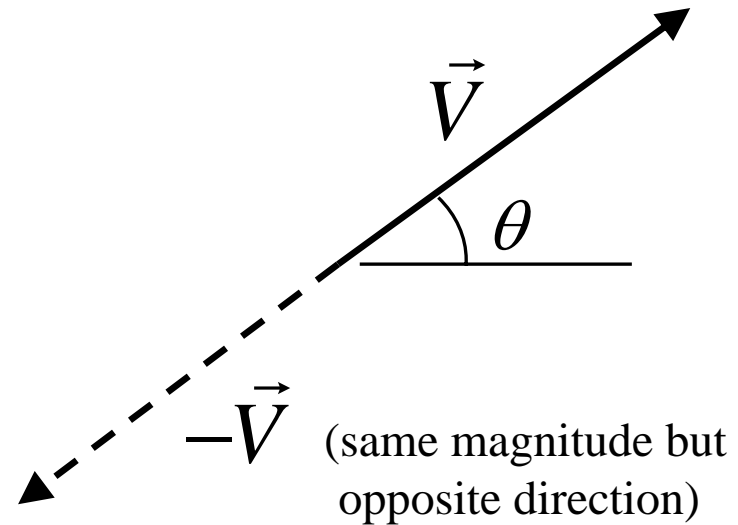
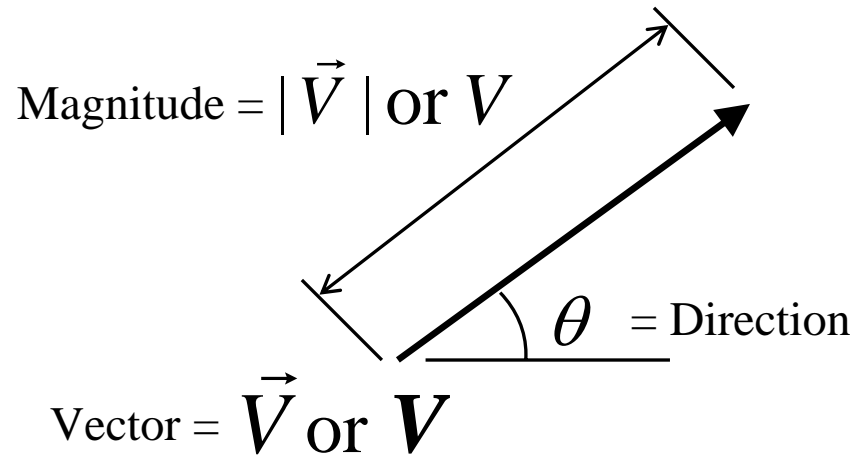
## Fixed vector

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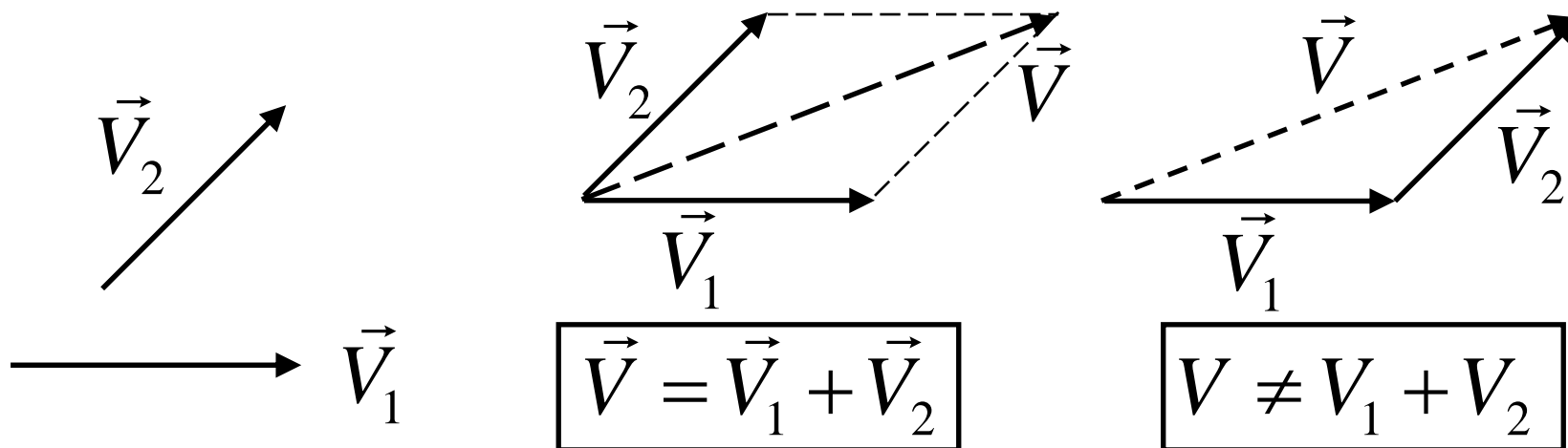
# Vector basics (1)

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- **Representation**



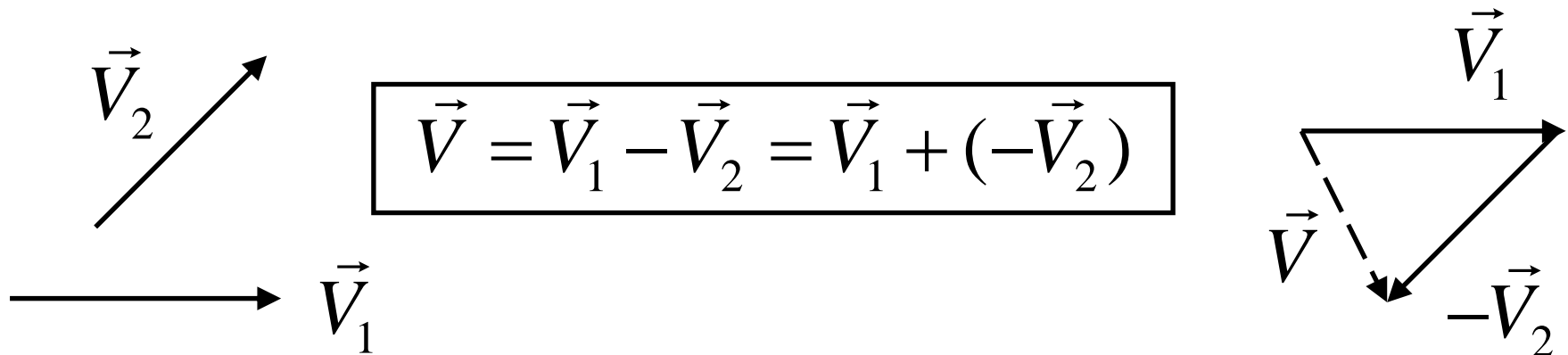
- **Addition (parallelogram law)**



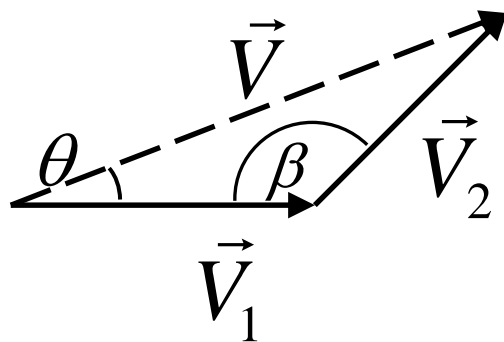
# Vector basics (2)

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- **Subtraction**



- **Basic relations**



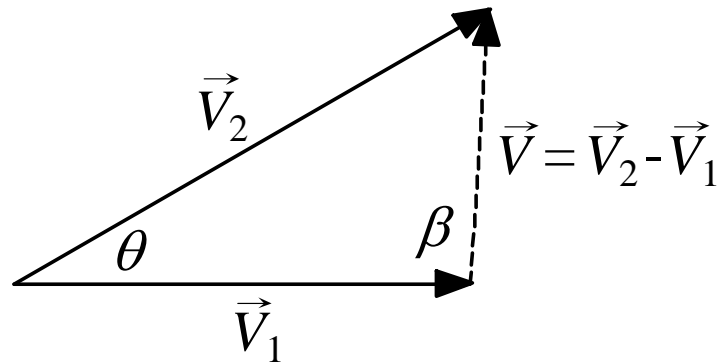
$$V^2 = V_1^2 + V_2^2 - 2V_1V_2 \cos(\beta)$$

$$\frac{V_2}{\sin(\theta)} = \frac{V}{\sin(\beta)}$$



# Example (1)

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Given:  $V_2 = 12$ ,  $V_1 = 10$   
 $\theta = 30^\circ$

Find:  $V$  and  $\beta$

cosine law  $V^2 = V_1^2 + V_2^2 - 2V_1V_2 \cos(\theta)$

$$V^2 = 10^2 + 12^2 - 2(10)(12) \cos(30^\circ)$$

$$V = 6.013$$

sine law  $\frac{V_2}{\sin \beta} = \frac{V}{\sin \theta} \longrightarrow \frac{12}{\sin \beta} = \frac{6.013}{\sin 30^\circ}$

$$\beta = 86.26^\circ, 93.74^\circ$$

# Example (2)

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Check by cosine law

$$\beta = 86.26^\circ$$

$$\begin{aligned} \text{cosine law} \quad 12^2 &= 10^2 + 6.013^2 - 2(10)(6.013)\cos(86.26^\circ) \\ 144 &\neq 128 \end{aligned}$$

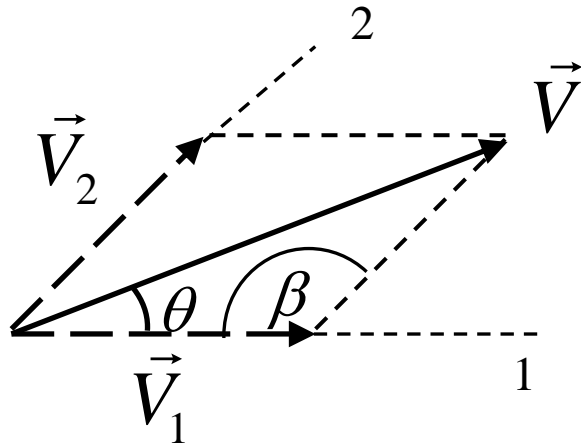
$$\beta = 93.74^\circ$$

$$\begin{aligned} \text{cosine law} \quad 12^2 &= 10^2 + 6.013^2 - 2(10)(6.013)\cos(93.74^\circ) \\ 144 &= 144 \quad \longrightarrow \quad \mathbf{OK} \end{aligned}$$

$\therefore V = 6.013, \beta = 93.74^\circ \longrightarrow \underline{\text{Ans}}$
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# Vector basics (3)

- **Components**

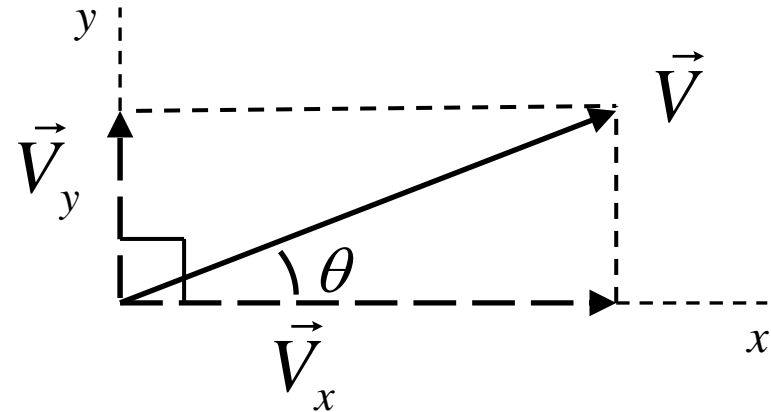


Given  $V$ ,  $\theta$  and  $\beta$ , we have

$V_1$        $\longrightarrow$       Sine law

$V_2$        $\longrightarrow$       Sine law

## Rectangular Components



$$V_x = V \cos(\theta)$$

$$V_y = V \sin(\theta)$$

$$V = \sqrt{V_x^2 + V_y^2}$$

$$\theta = \tan^{-1}(V_y / V_x)$$

# Vector basics (4)

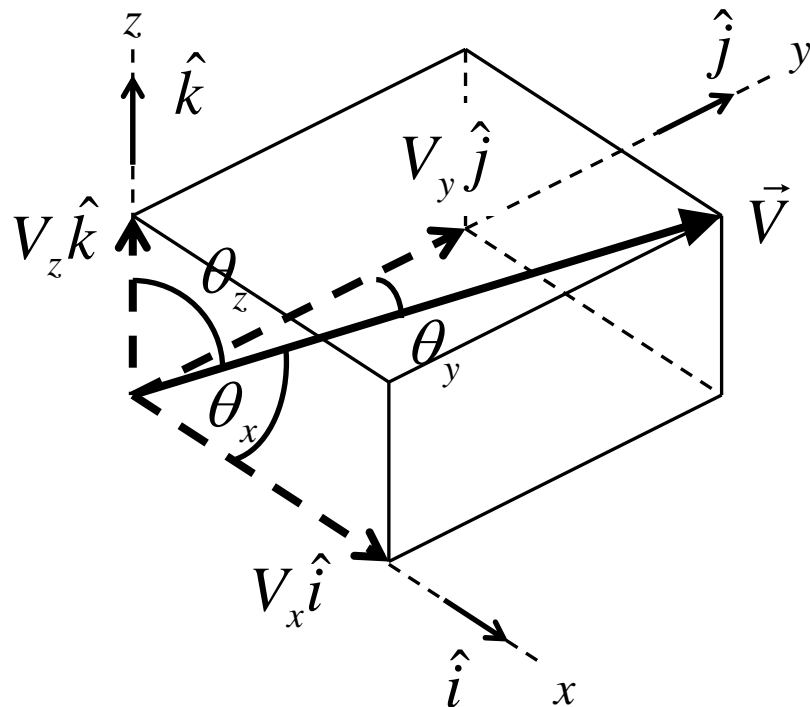
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## Unit vector

$$\vec{V} = V\hat{n} \quad , \quad \hat{n} = \text{unit vector; (magnitude = 1, same direction as } \vec{V} \text{)}$$

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## 3D Rectangular component



$$\vec{V} = V_x \hat{i} + V_y \hat{j} + V_z \hat{k}$$

$$V_x = V \cos(\theta_x)$$

$$V_y = V \cos(\theta_y)$$

$$V_z = V \cos(\theta_z)$$

$$V^2 = V_x^2 + V_y^2 + V_z^2$$

$$1 = \cos^2(\theta_x) + \cos^2(\theta_y) + \cos^2(\theta_z)$$

# Newton's Laws (1)

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## Law 1

“A particle remains at rest or continues to move in a straight line with a uniform velocity if there is no unbalanced force acting on it.”

$$\vec{a} = 0 \quad \Leftrightarrow \quad \sum \vec{F} = 0$$

## Law 2

“The acceleration of a particle is proportional to the resultant force acting on it and is in the direction of this force.”

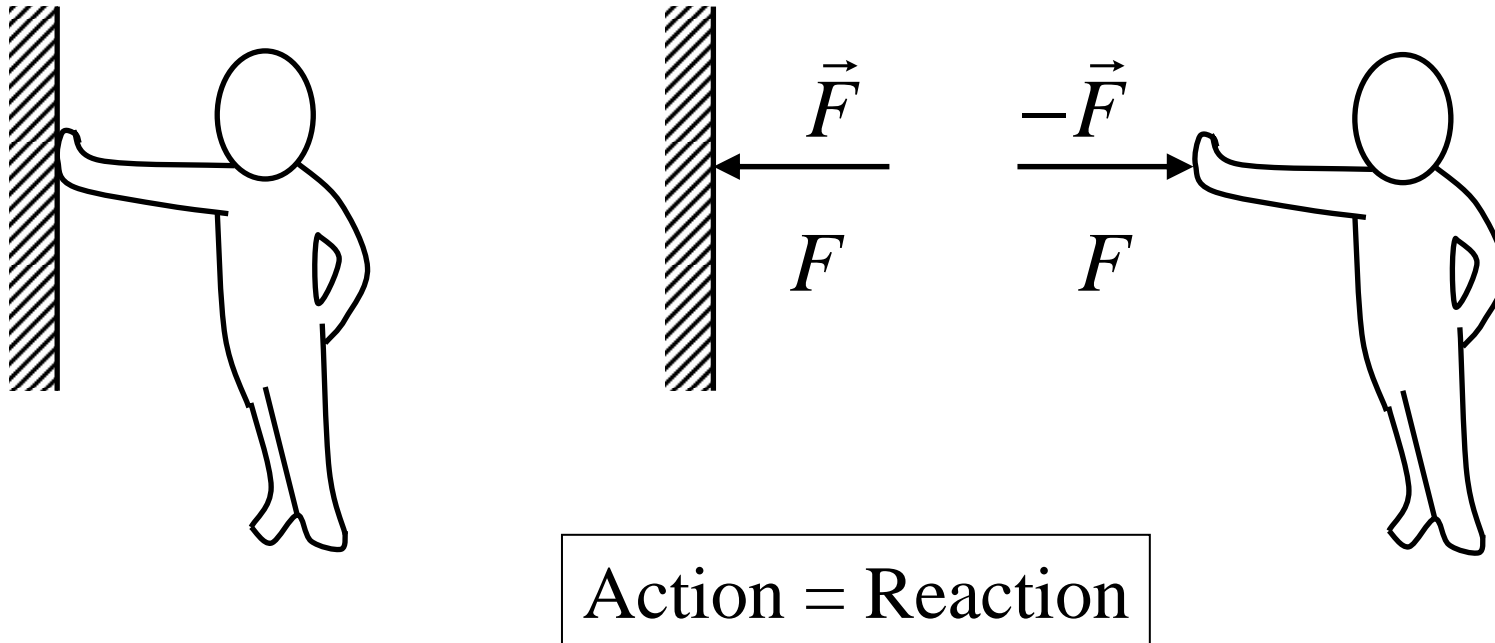
$$\sum \vec{F} = m\vec{a}$$

# Newton's Laws (2)

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## Law 3

“The force of action and reaction between interacting bodies are equal in magnitude, opposite in direction, and collinear.”



**\* Action and reaction are acting on different bodies.**