

Best Practices in Code Inspection for Safety-Critical Software

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```
/* 1. routine return methods */
```

```
int a (int b)
{
    if (b == 0)
    {
        d = 1;
        return 0;
    }
    else
    {
        if (b == 1)
            d = 3;
        // this path does not return a value
        else
            return 1;
    }
}
```

```
/* 2. interrupt-handling routines and critical regions */
```

```
void
interrupt int_rx(void)
{
    if (n_queue == MAX) return;
    // this path is dangerous
    queue[n_queue++] = inport (P_ADDRESS);
    outport(EOI, EOIVALUE);
}
```

```
interrupt void insert(void)
```

```
{
    char new;
    new = inp(0xf3);
    queue[filas[pos]] = new;
    pos++;
}
```

```
char remove(void)
```

```
{
    char ret;
    if (pos == 0) return -1;
    ret = queue[pos];
    pos--;
    return ret;
}
```

```
/* 3. repetitive-loop control */
```

```
void a (int b)
{
    char i;
    static c[256];
    for (i = b; i > 0; i--)
        c[i] = 0;
}
```

```
void a (int b)
{
    char i;
    for (i = 0; i < b; i++)
        c[i] = 0;
}
```

```
/* 4. I/O tests */
```

```
void
routine(void)
{
    static int    IO_Test = 0;

    if (IO_Test) fail();
    IO_Test = 1;
    /* routine body */
    if (!IO_Test) fail();
    IO_Test = 0;
}
```

```
/* 5. program flow control */
```

```
if sel > 3 then
    call fail;
else do case sel;
    do;    /* case 0 */
    end;
    do;    /* case 1 */
    end;
    do;    /* case 2 */
    end;
end;

switch (a)
{
    case 0:
        b = 1;
        break;
    case 2:
        b = 6;
    case 3:
        b = 7;
        break;
}
```

```

/* 7. variables and constants */
ex:1
    if (i > MAX) fail();
        // lower limit not verified
    queue[i] = queue[i+1];
        // i+1 may be out of bounds
ex:2
file #1:
    MAX EQU        $2F
    ; assembly declaration in decl.equ

file #2:
    #define        MAX    48
    // C declaration i ext.h

ex:3
extern char *test;
    //declaration in file test.h

int    test[80];
    // declaration in file test.c

/* 9. source code legibility */
BYTE Mode;
    #define        MIN_Temperature 32

BYTE *pMode;
    #define        MAX_Temperature 212

```