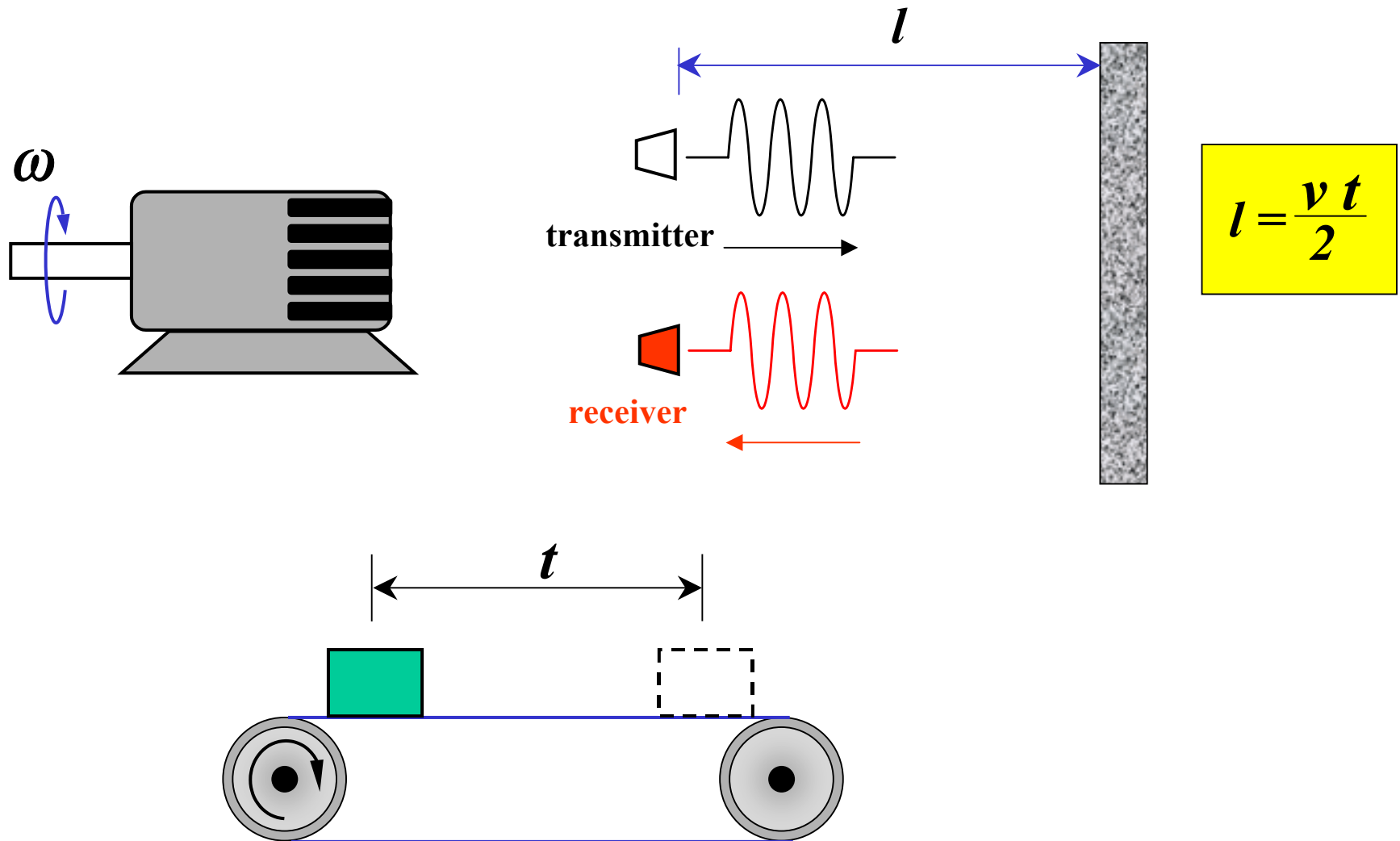
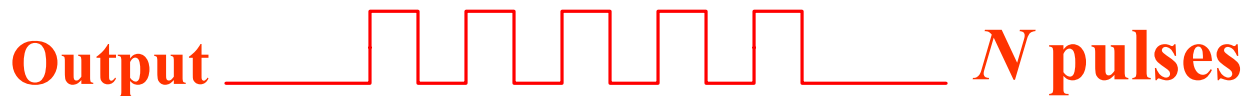
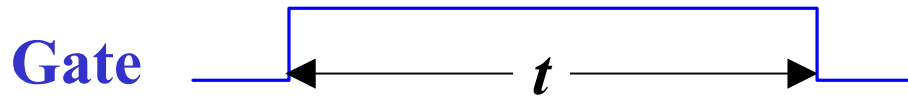
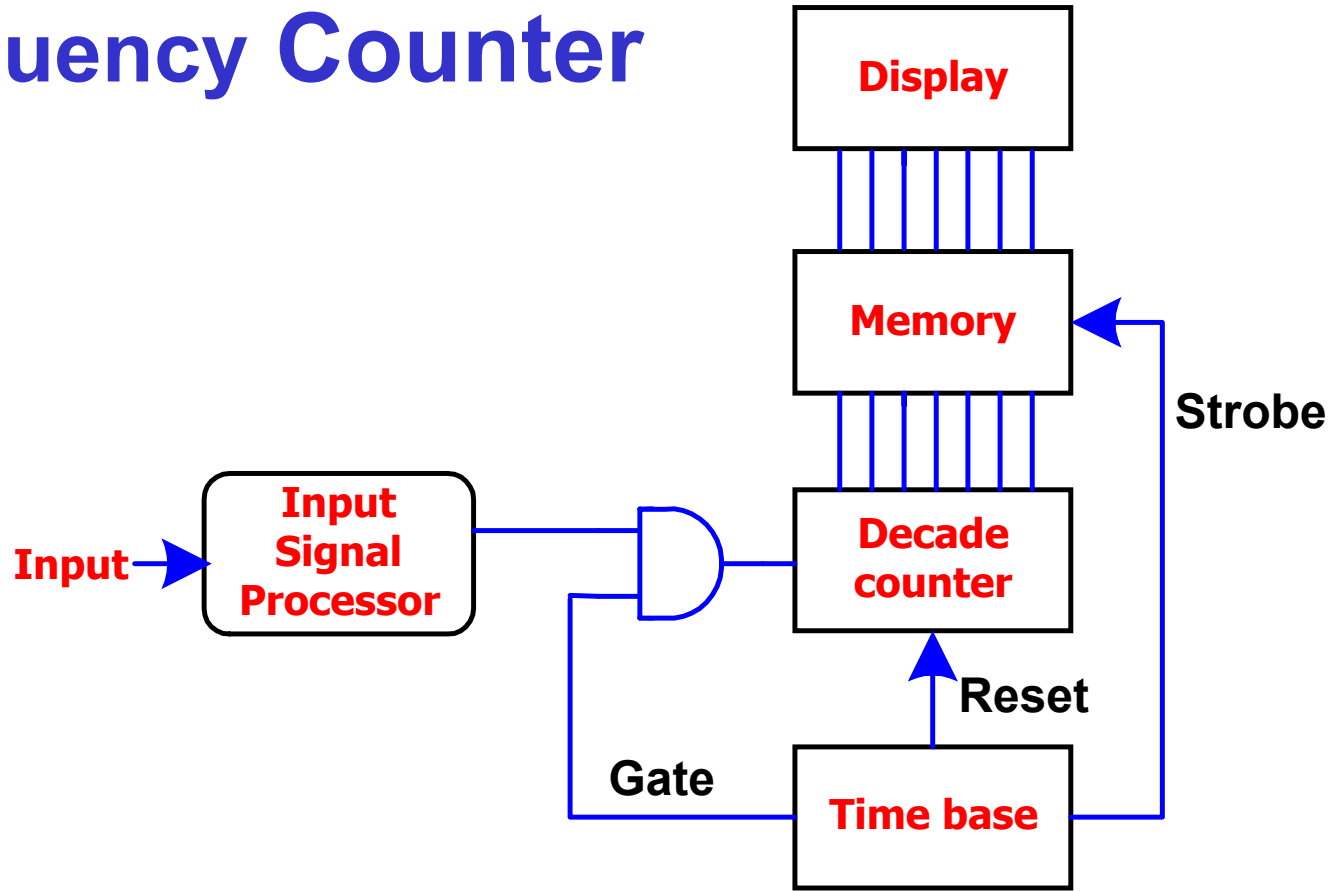


# Frequency and Period Measurement

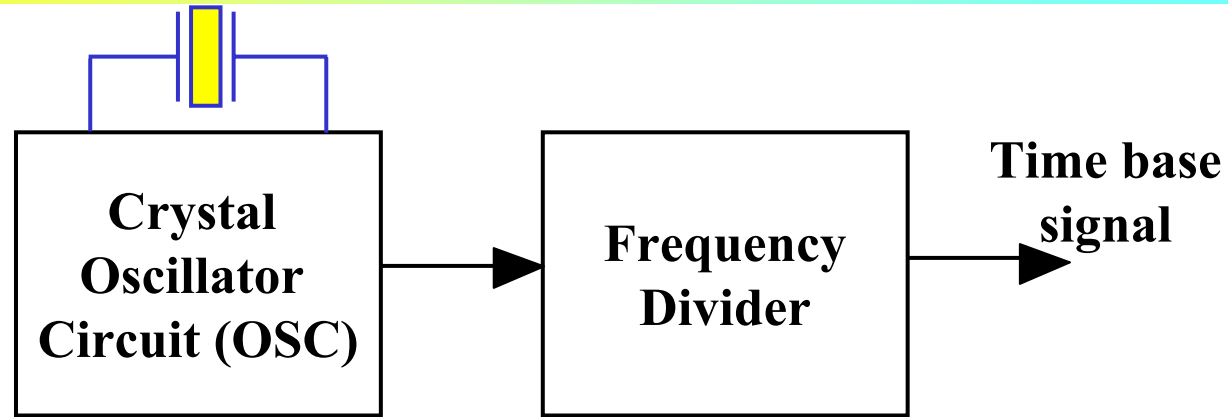


# Frequency Counter



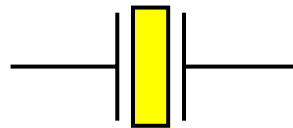
$$f = \frac{N}{t}$$

# Time Base

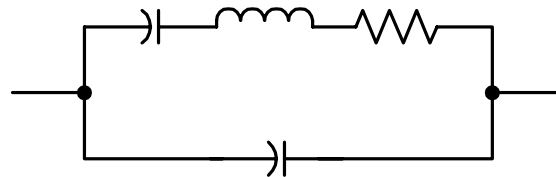


- **Non-compensated OSC**
- **Temp. compensated OSC**
- **Oven-type OSC**

## Quartz crystal

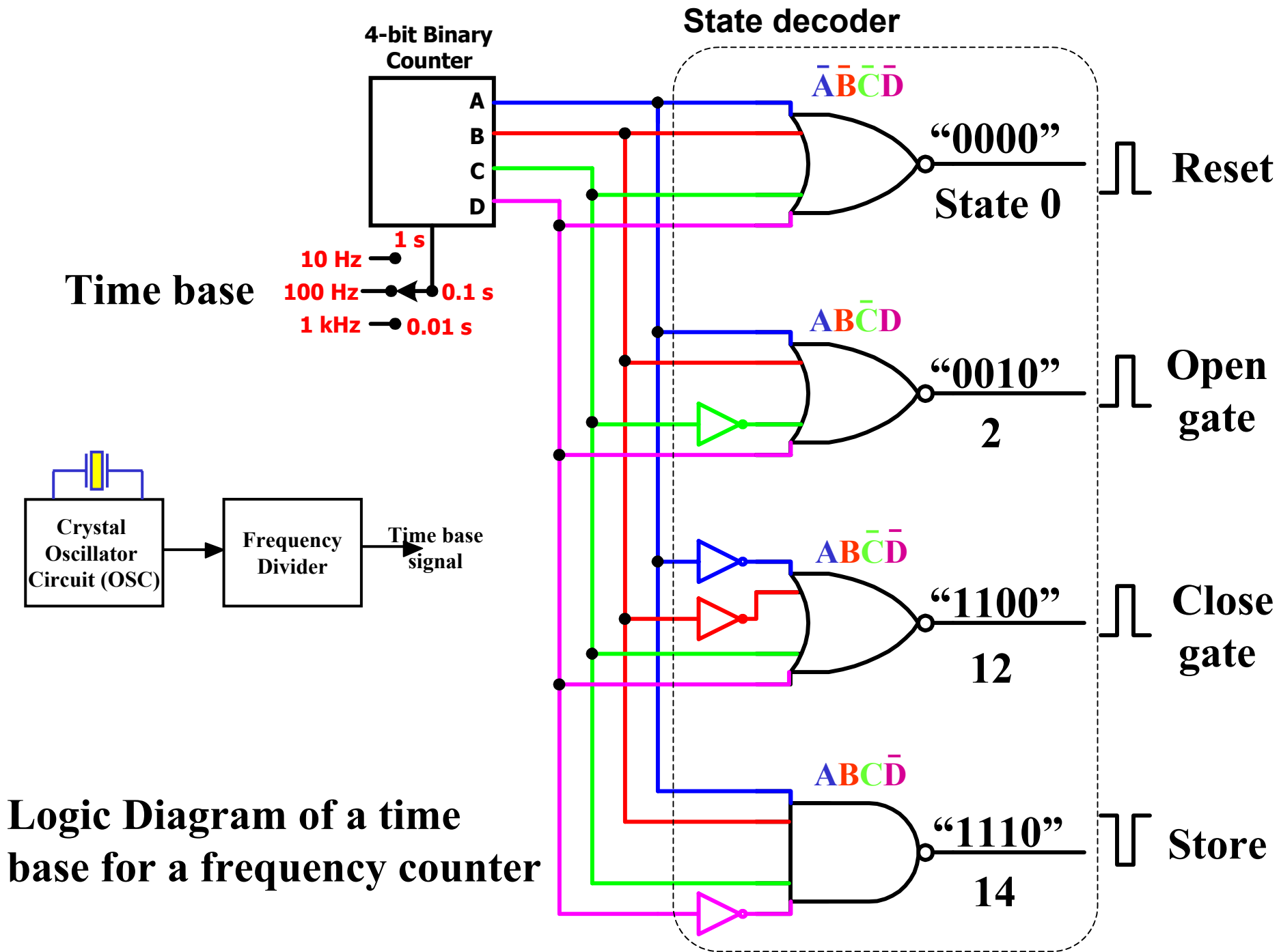


**symbol**

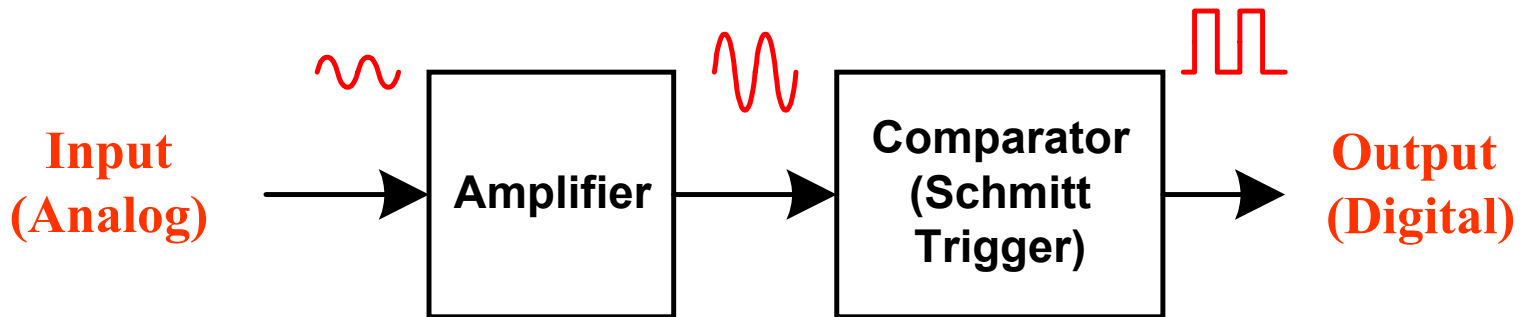
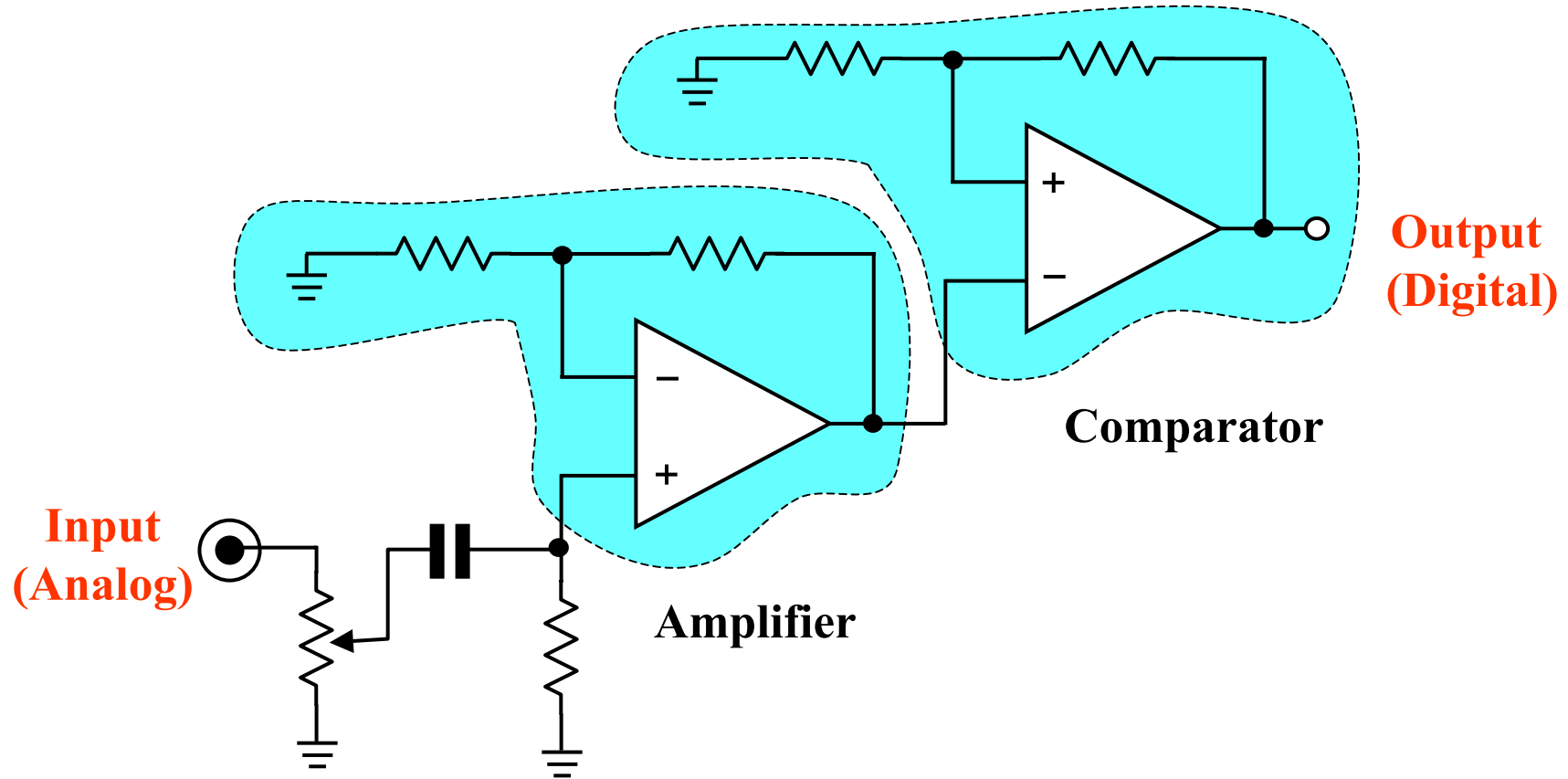


**Equivalent circuit**

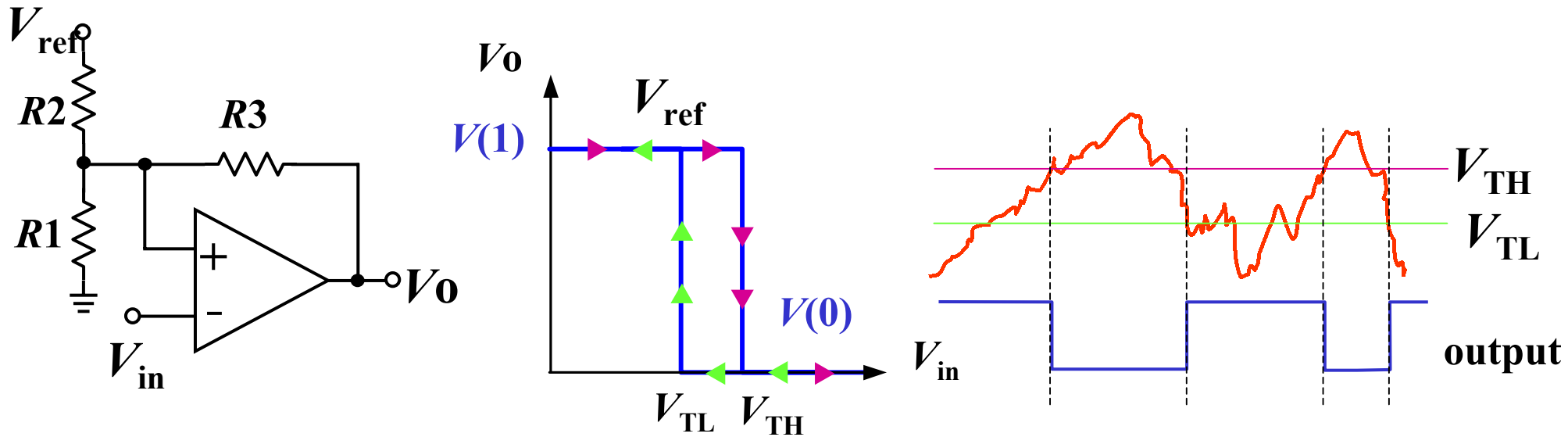
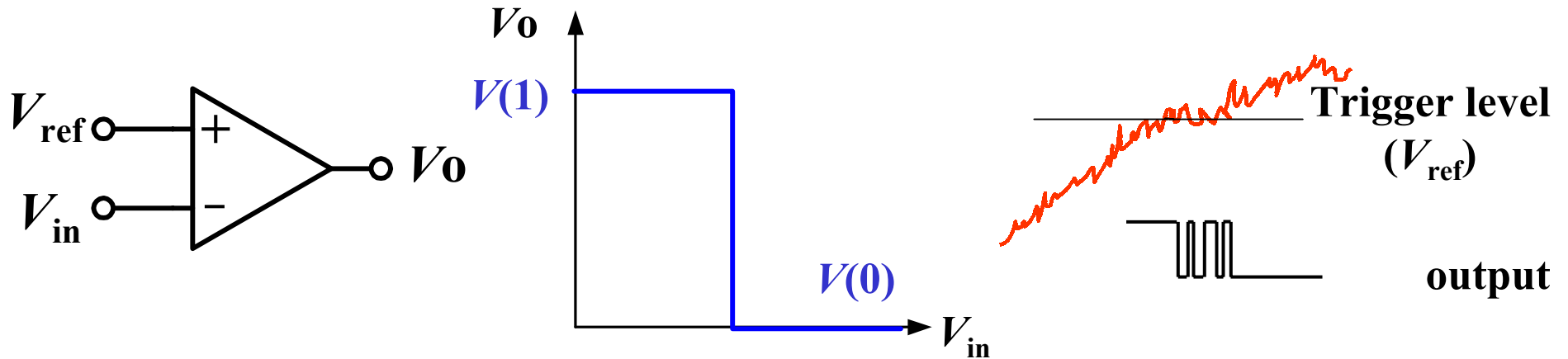
**High Q ~ 10000**



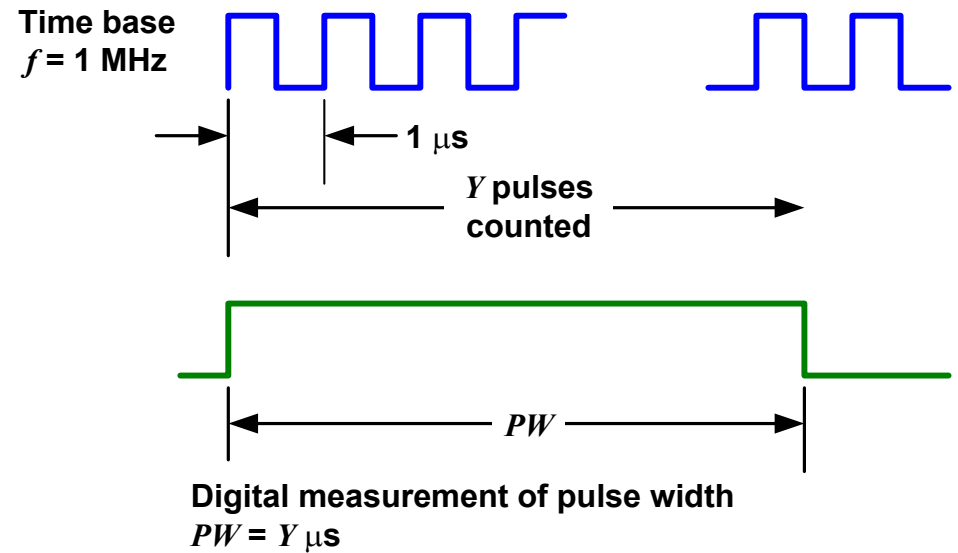
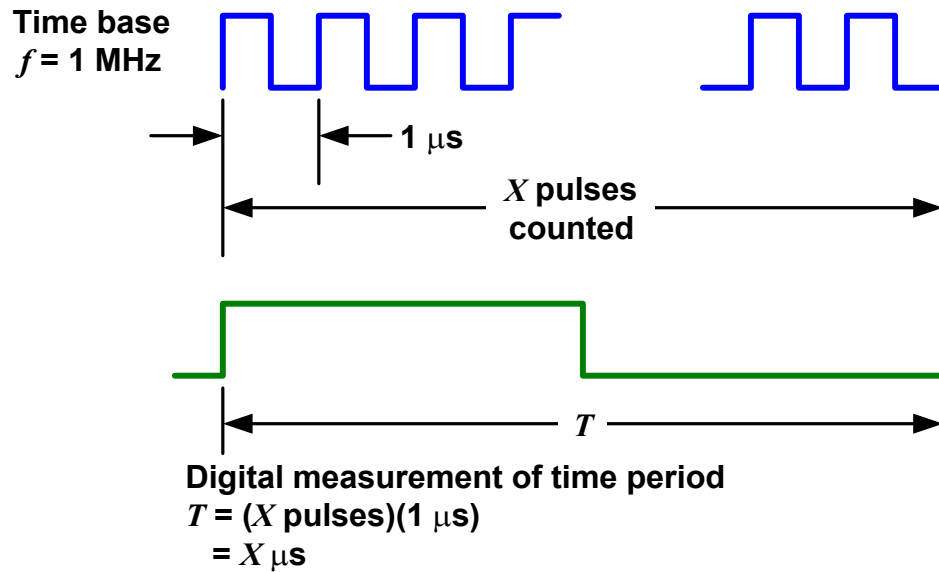
# Input Signal Processing



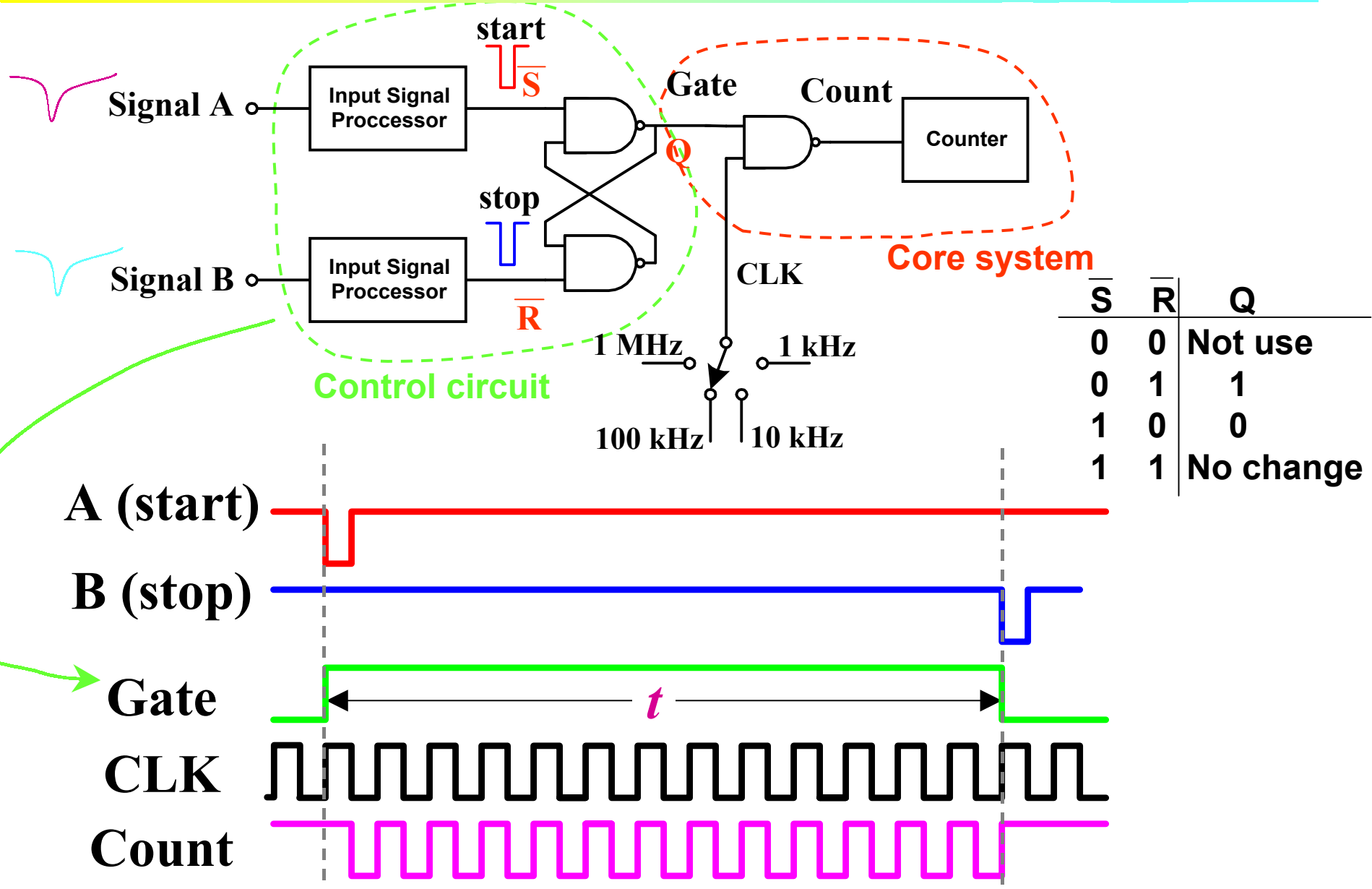
# Schmitt Trigger: Comparator with Hysteresis



# Period Measurement

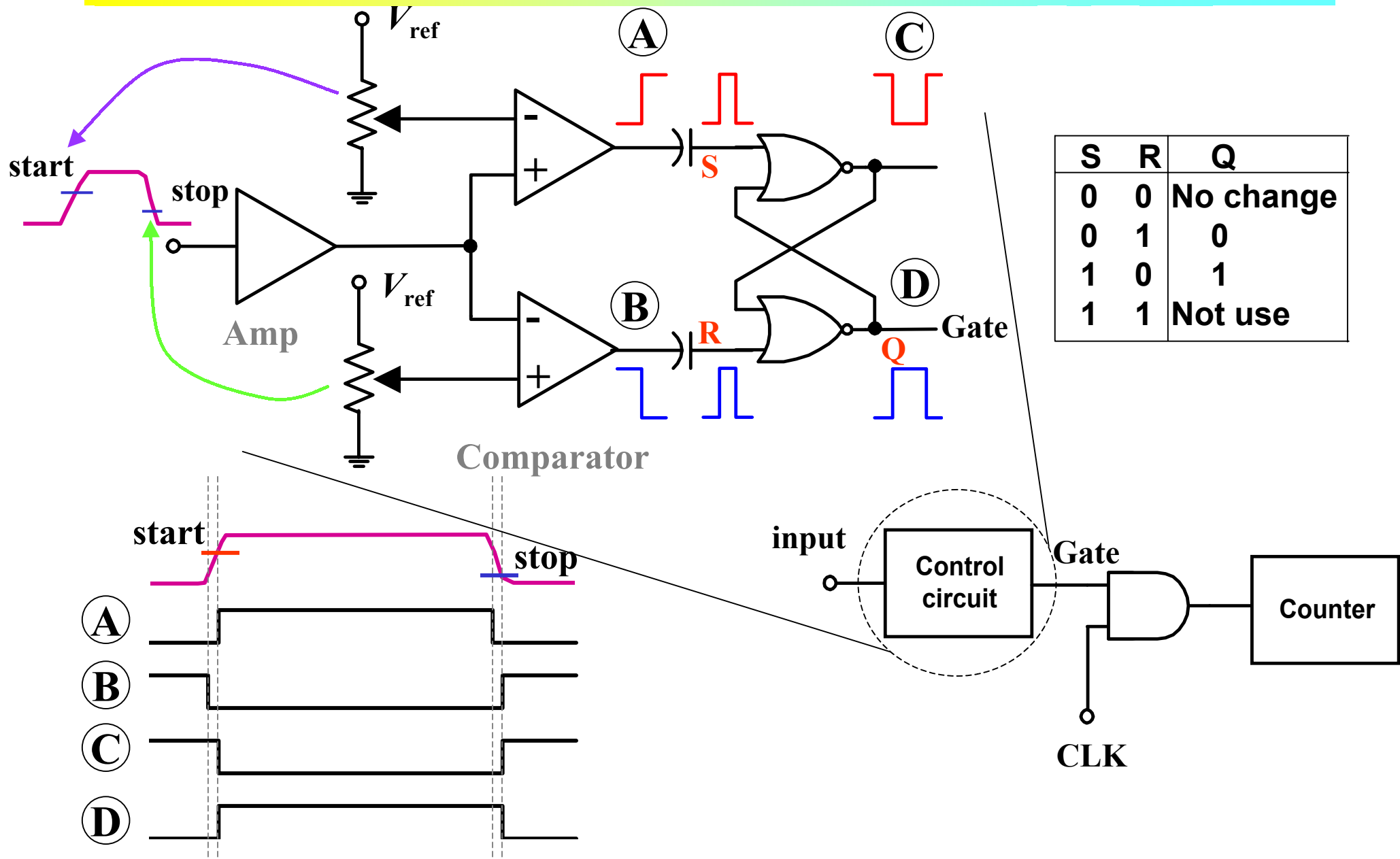


# Period Measurement (between pulses)

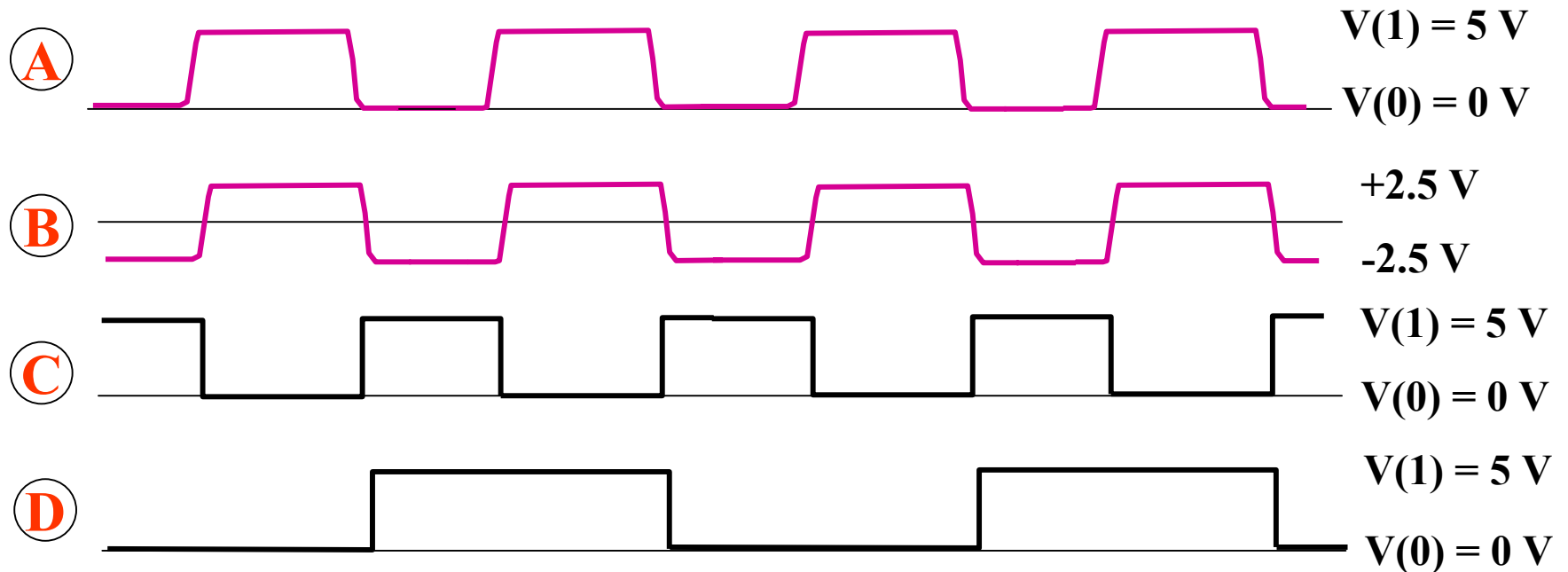
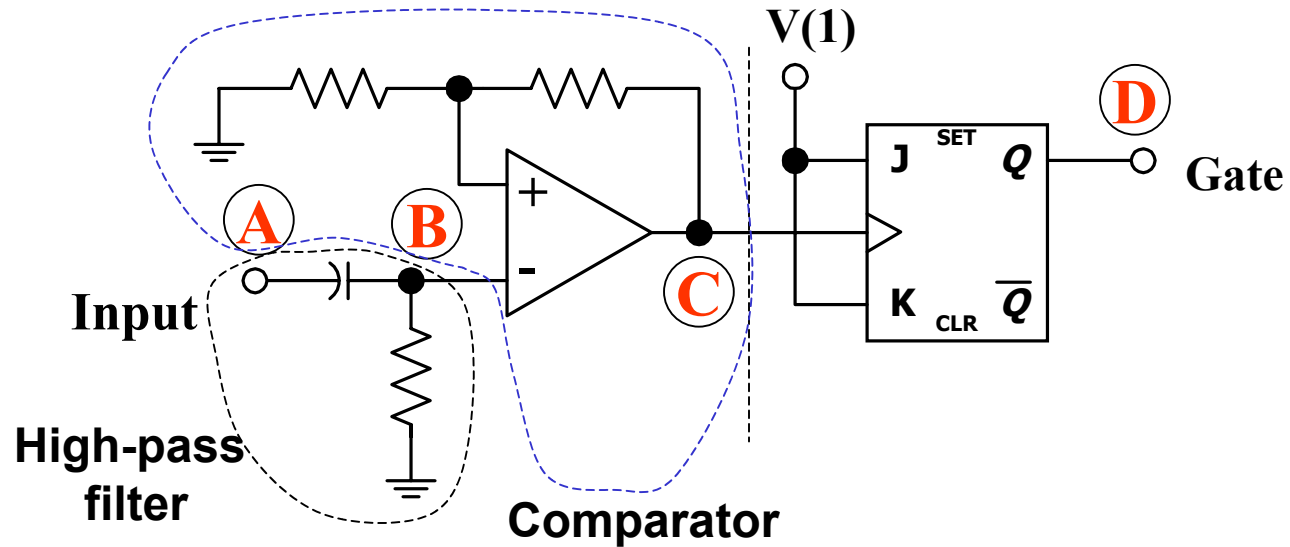




# Period Measurement (pulse duration)

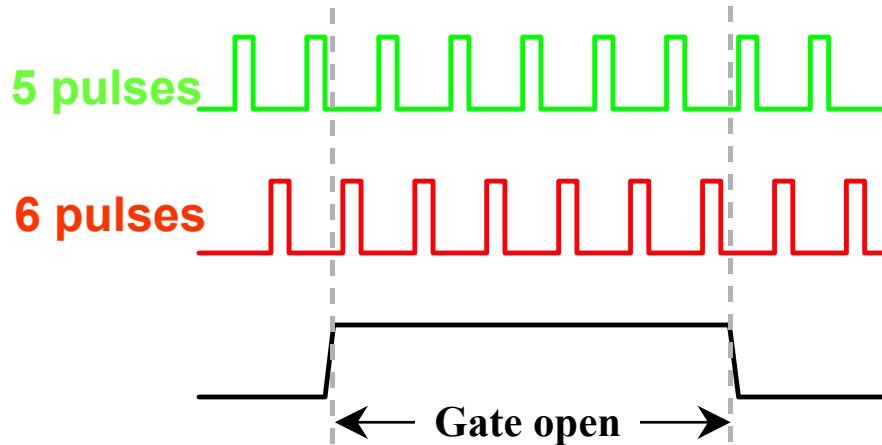


# Period Measurement (pulse period)



# Measurement Error

## 1) Gating error ( $\pm 1$ count)



Frequency measurement

If  $f_{in} = 10$  Hz, Gate time = 1 s

Display count:  $10 \pm 1$  counts

If  $f_{in} = 1000$  Hz, Gate time = 1 s

Display count:  $1000 \pm 1$  counts

If  $f_x < f_0$  Period measurement  
if  $f_x > f_0$  Frequency measurement

$f_c$ : clock frequency     $f_x$ : unknown frequency

Period meas.: the number of pulses ( $N_p$ )

$$N_p = f_c / f_x$$

Frequency meas.: with 1 s gate time the number of pulses ( $N_f$ )

$$N_f = f_x$$

The crossover frequency ( $f_0$ )  $N_p = N_f$

$$f_c / f_0 = f_0; f_0 = \sqrt{f_c}$$

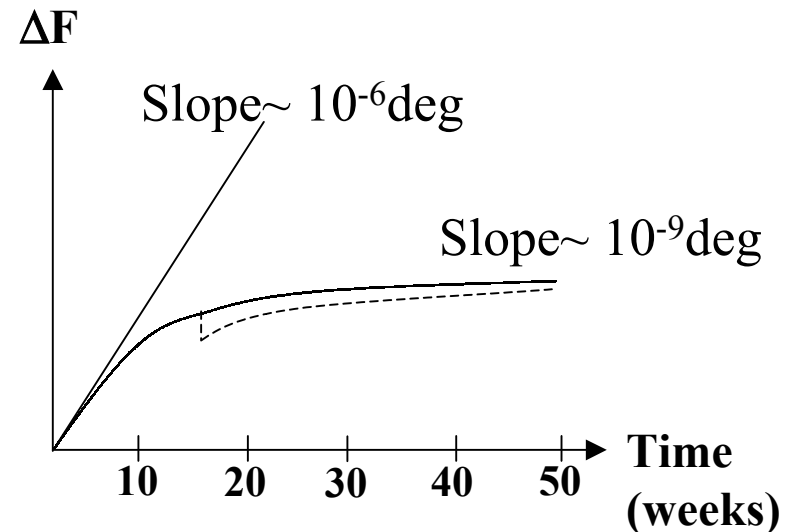
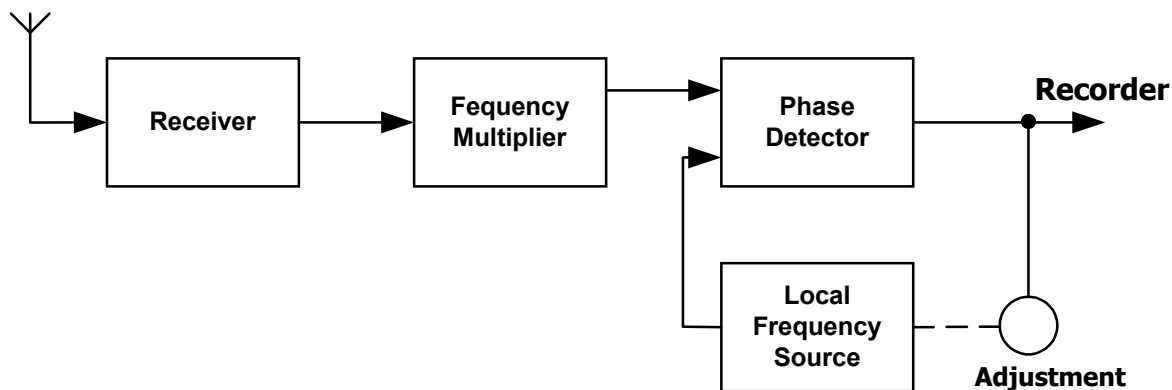
# Measurement Error

## 2) Time-base Error

- **Oscillator calibration errors**
- **Short-term crystal stability errors**  
(voltage transient, shock, vibrate, temperature)
- **Long-term crystal stability errors**  
(aging, deterioration of crystal)

National Institute of Standards and Technology, 60 kHz

Loran-C, a navigation signal at 100 kHz



**Ex** A frequency counter with an accuracy of  $\pm 1 \text{ LSD} \pm (1 \times 10^{-6})$  is employed to measure frequencies of 100 Hz, 1 MHz, and 100 MHz. Calculate the percentage measurement error in each case.

At  $f = 100 \text{ Hz}$

$$\begin{aligned}\text{error} &= \pm (1 \text{ count} \pm 100 \text{ Hz} \times 10^{-6}) \\ &= \pm (1 \text{ count} \pm 1 \times 10^{-4} \text{ count}) \\ &\approx \pm 1 \text{ count}\end{aligned}$$

$$\begin{aligned}\% \text{ error} &= \pm \left( \frac{1}{100 \text{ Hz}} \times 100\% \right) \\ &= \pm 1\%\end{aligned}$$

At  $f = 1000 \text{ Hz}$

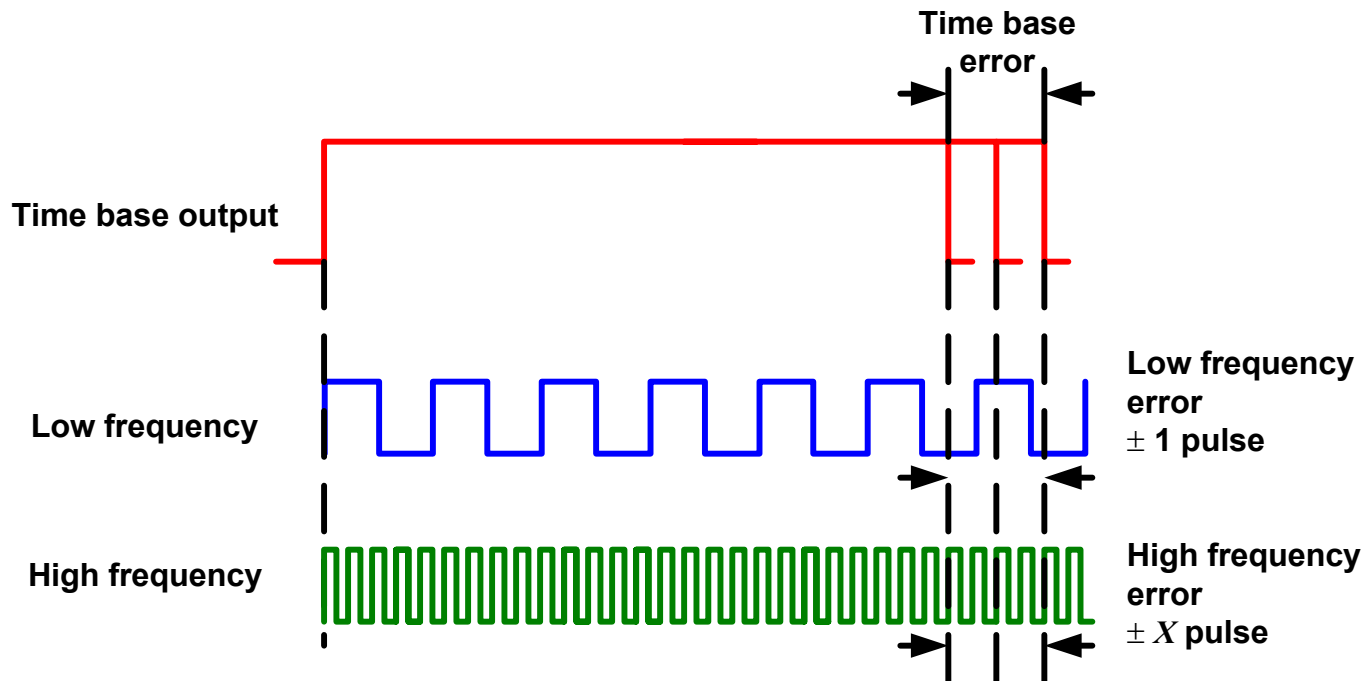
$$\begin{aligned}\text{error} &= \pm (1 \text{ count} \pm 1 \text{ MHz} \times 10^{-6}) \\ &= \pm (1 \text{ count} \pm 1 \text{ count}) \\ &= \pm 2 \text{ count}\end{aligned}$$

$$\begin{aligned}\% \text{ error} &= \pm \left( \frac{2}{1 \text{ MHz}} \times 100\% \right) \\ &= \pm 2 \times 10^{-4} \%\end{aligned}$$

At  $f = 100 \text{ MHz}$

$$\begin{aligned} \text{error} &= \pm (1 \text{ count} \pm 100 \text{ MHz} \times 10^{-6}) \\ &= \pm (1 \text{ count} \pm 100 \text{ count}) \\ &= \pm 101 \text{ count} \end{aligned}$$

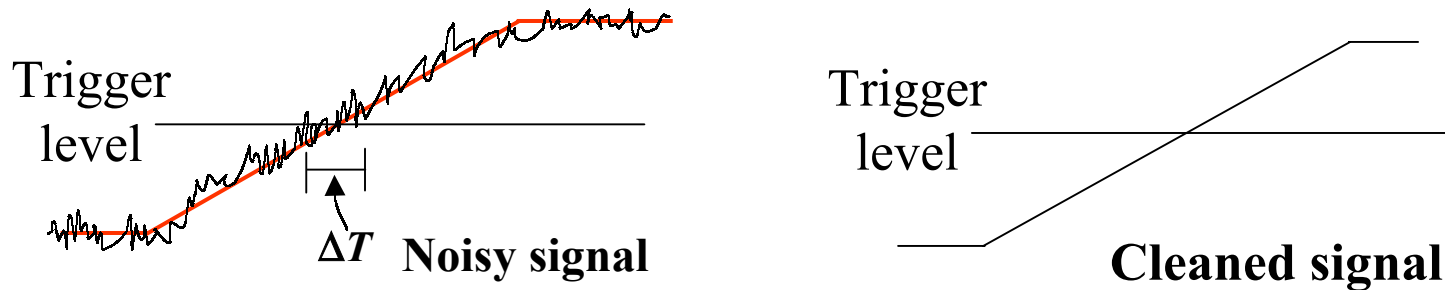
$$\begin{aligned} \% \text{ error} &= \pm \left( \frac{101}{100 \text{ MHz}} \times 100\% \right) \\ &= \pm 1.01 \times 10^{-4} \% \end{aligned}$$



# Measurement Error

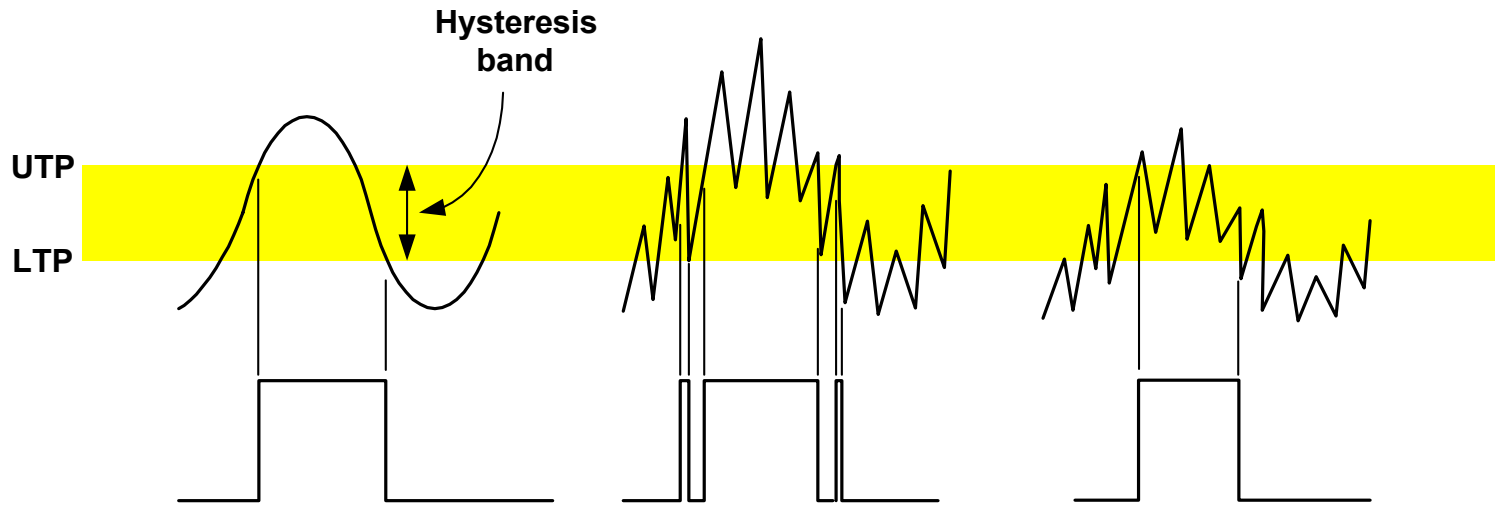
## 3) Trigger Level Error (Noise)

**-Use large signal amplitudes and fast rise time**



**Maximum accuracy could be obtained by**

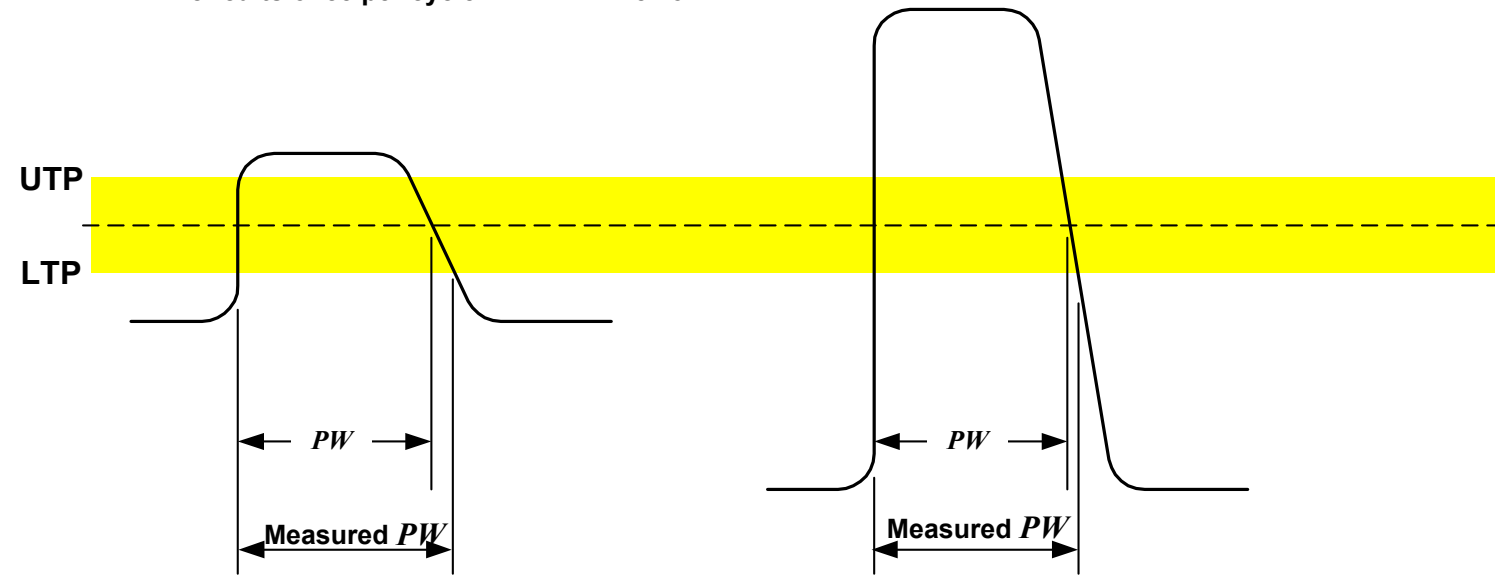
- 1) use period measurement if  $f_x < f_c$   
use frequency measurement if  $f_x > f_c$**
- 2) Calibrate regularly to prevent long-term stability error**
- 3) Reduce trigger level error in time measurement by using large signal and fast rise time**



'clean' sine wave crosses the hysteresis band twice during each cycle - triggering counting circuits once per cycle

Noisy sine wave crosses the hysteresis band more than twice during each cycle - produce counting error

Attenuated noisy wave form crosses the hysteresis band twice during each cycle



A low amplitude input pulse can produce errors in pulse width measurement

Amplification of the input pulse minimizes the pulse width measurement



Ex จงหา resolution และค่าความถี่สูงสุดที่สามารถแสดงผลได้ในเครื่องวัด  
ความถี่ที่มีการแสดงผลแบบ 7 หลัก ถ้าเวลาของสัญญาณเกิดถูกตั้งไว้ที่ 1  
วินาที (resolution = 1 Hz, Max. freq. = 9,999,999 Hz)

Ex เครื่องวัดความถี่เครื่องหนึ่งมีความผิดพลาดจากการนับ  $\pm 1$  ครั้ง ( $\pm 1$  count)  
และมีความผิดพลาดจากฐานเวลา 5 ส่วนในล้านส่วน (ppm: part per million)  
จงหาค่าเปอร์เซ็นต์ความผิดพลาดเมื่อใช้วัดความถี่ 1 kHz

ความผิดพลาดรวมเท่ากับผลรวมของความผิดพลาดทั้งสอง

$$\text{ความผิดพลาด} = \pm (1 \text{ count} + 1 \text{ kHz} \times 5 \text{ ppm})$$

$$= \pm (1 \text{ count} + 0.005 \text{ count})$$

$$\text{ค่าเปอร์เซ็นต์ความผิดพลาด} = \pm \frac{1.005}{1000} \times 100 = 0.1\%$$

# Specifications of a freq./period Measurement

---

## Frequency mode

**Range:** DC to 50 MHz

**Gate time:** Manual 1 ms to 100 s in decade step  
Automatic up to 1 s gate time

## Period mode

**Range:** 1  $\mu$ s to 1 s unit in  $\mu$ s

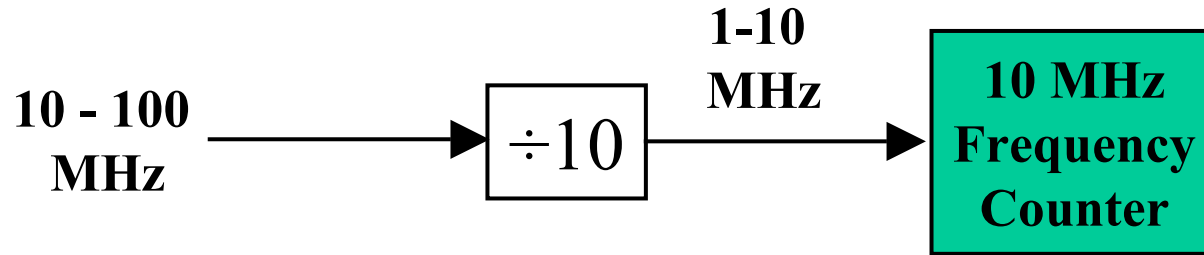
## Duration mode

**Range:** 100 ns to  $10^4$  s

**Inputs:** 2 channels for start signal and 1 channel for stop signal

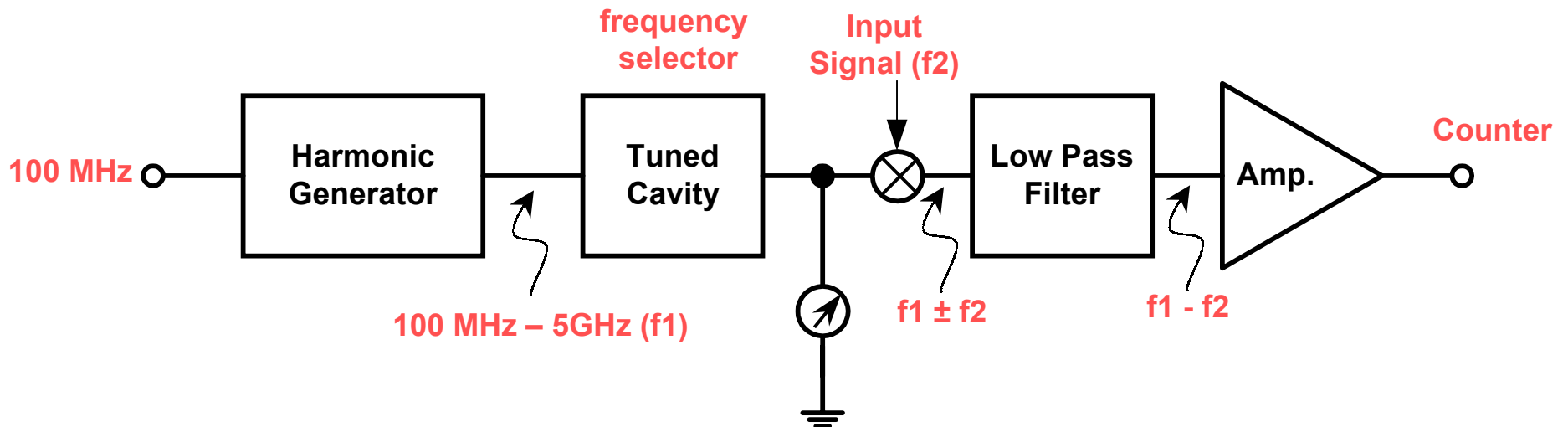
# Extending the frequency range of a counter

## ❖ Prescaler (upto 1.5 GHz)

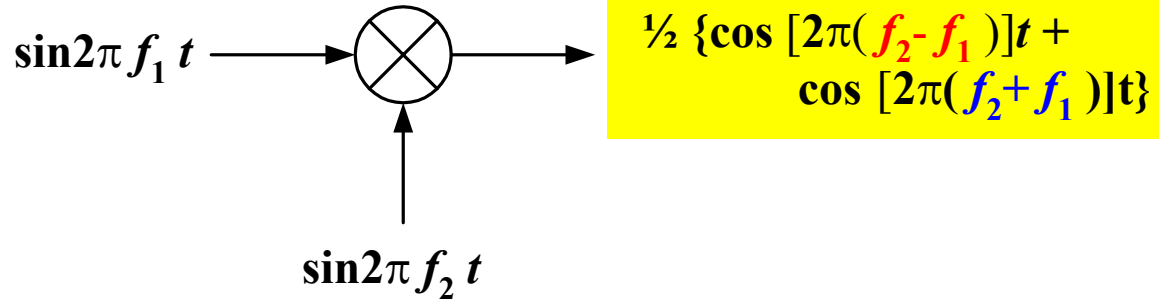


Reduce resolution but can be improved by extending gate time

## ❖ Heterodyne Technique

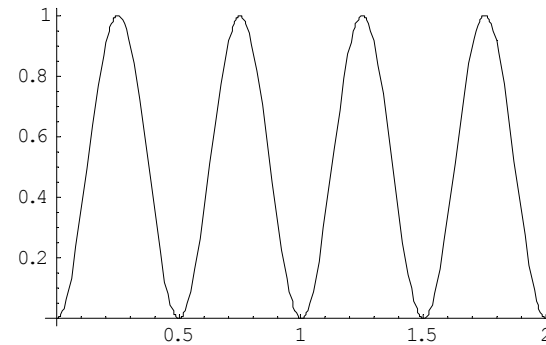
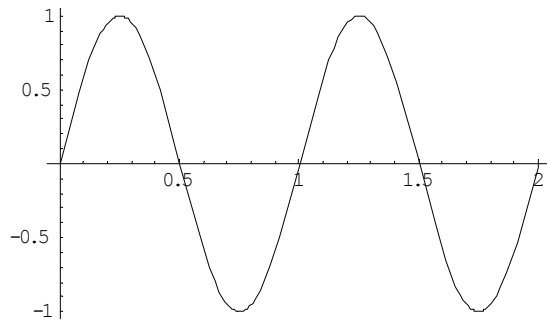


# Homodyne and Heterodyne technique

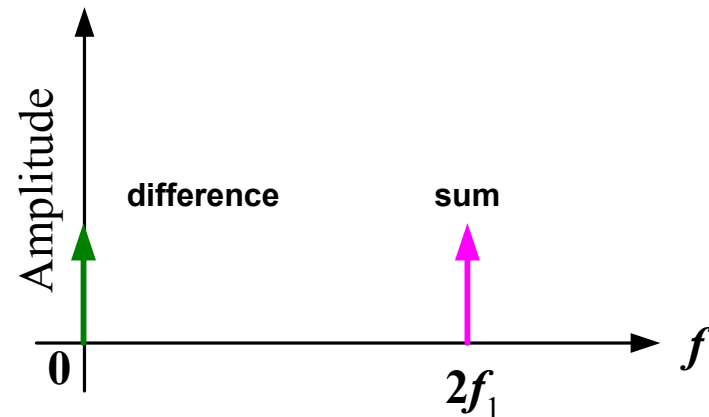
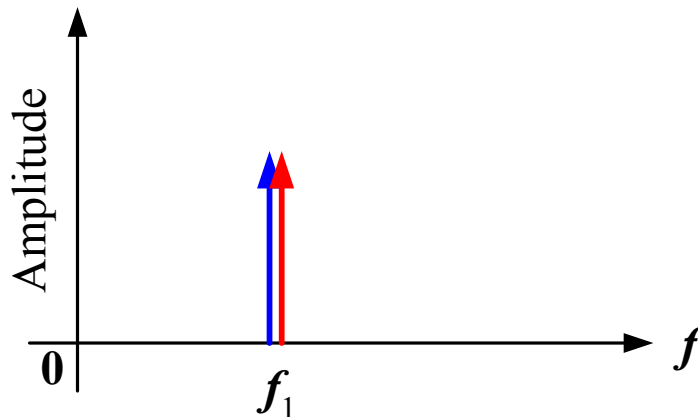


If  $f_1 = f_2$ ; Homodyne

Time domain



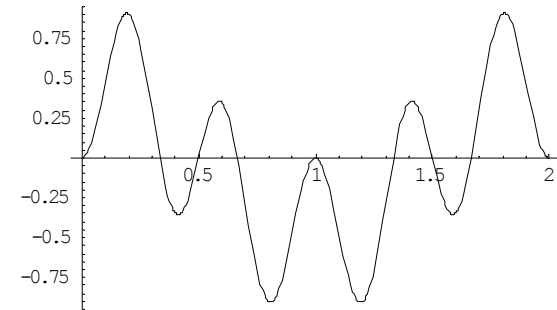
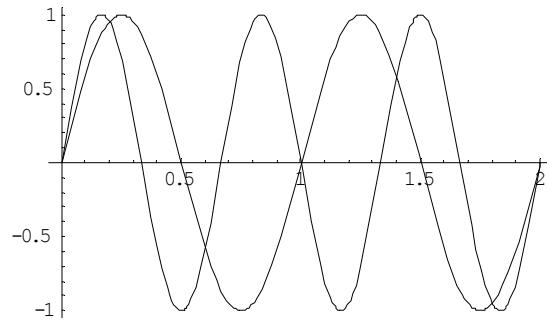
Frequency domain



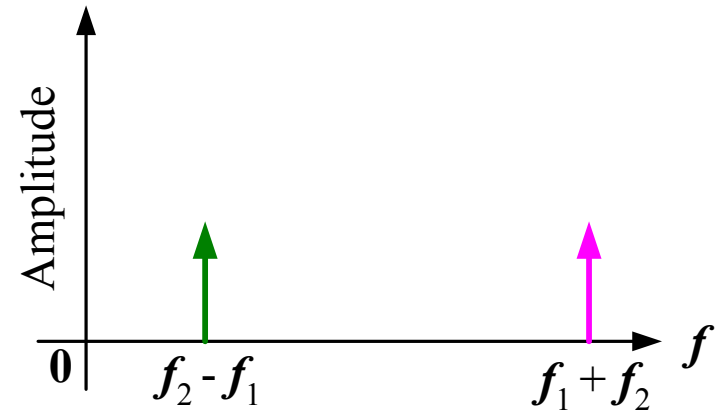
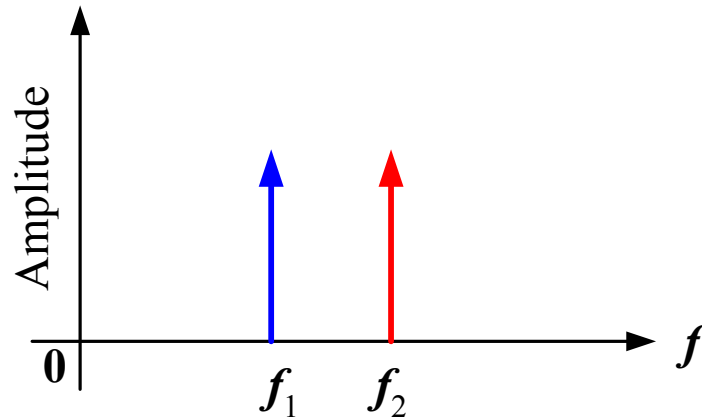
# Homodyne and Heterodyne technique

If  $f_1 \neq f_2$ ; Heterodyne

Time domain

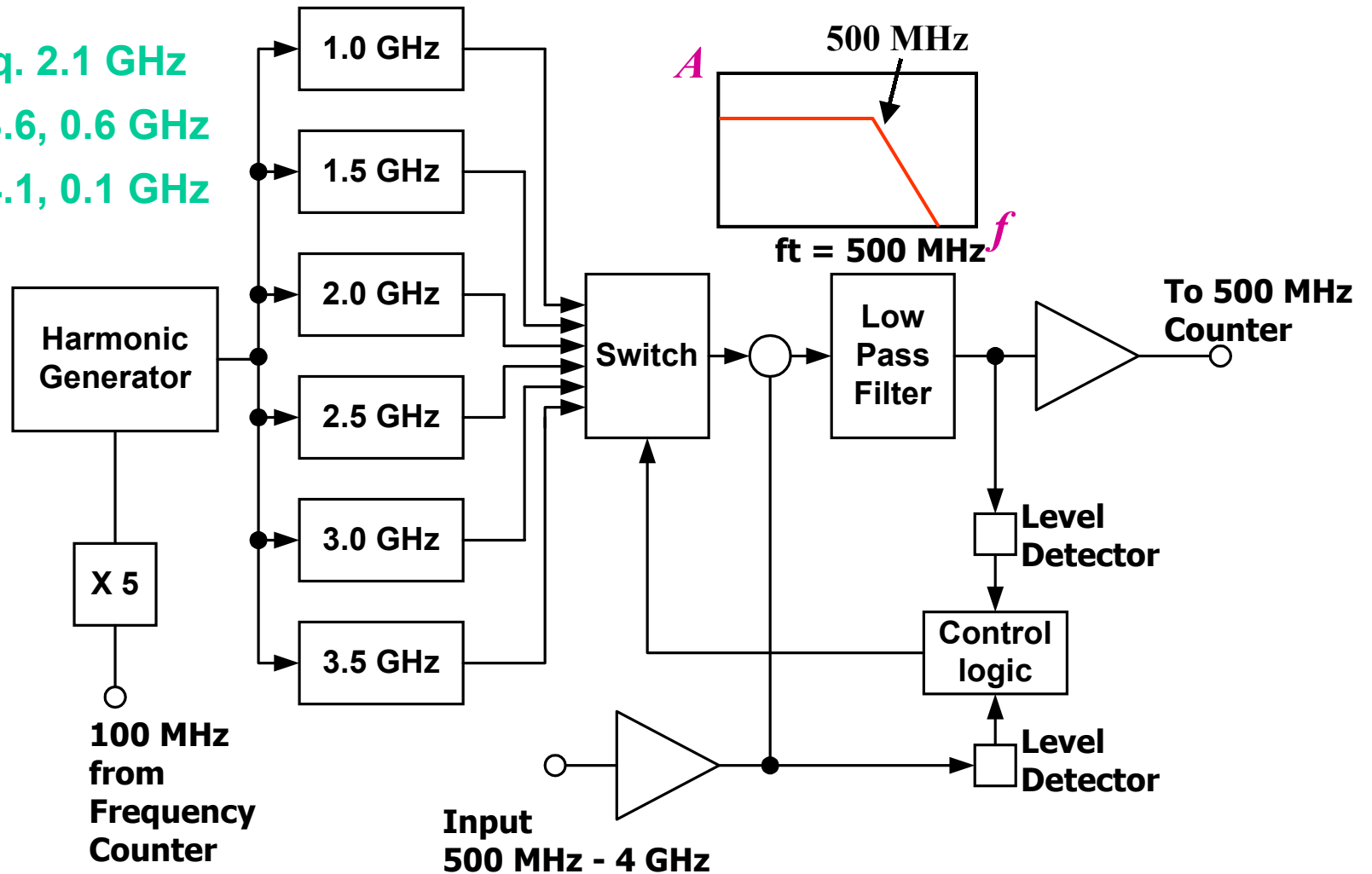


Frequency domain



# Automatic Heterodyne Unit

Ex input freq. 2.1 GHz  
 $1.5 \pm 2.1 = 3.6, 0.6$  GHz  
 $2.0 \pm 2.1 = 4.1, 0.1$  GHz



# Accuracy

## ❖ Prescaler

$$\text{Displayed freq.} = \frac{f_{\text{in}}}{N} t$$

$f_{\text{in}}$ : input freq.

$N$ : divider of prescaler

$t$ : gate time

**Accuracy  $\propto t$  exactly the same as the counter without a prescaler**

## ❖ Heterodyne Technique

$$\text{Gate time, } t = \frac{Q}{f_c}$$

$Q$ : Time-base Divisor

$f_c$ : Time-base Clk freq.

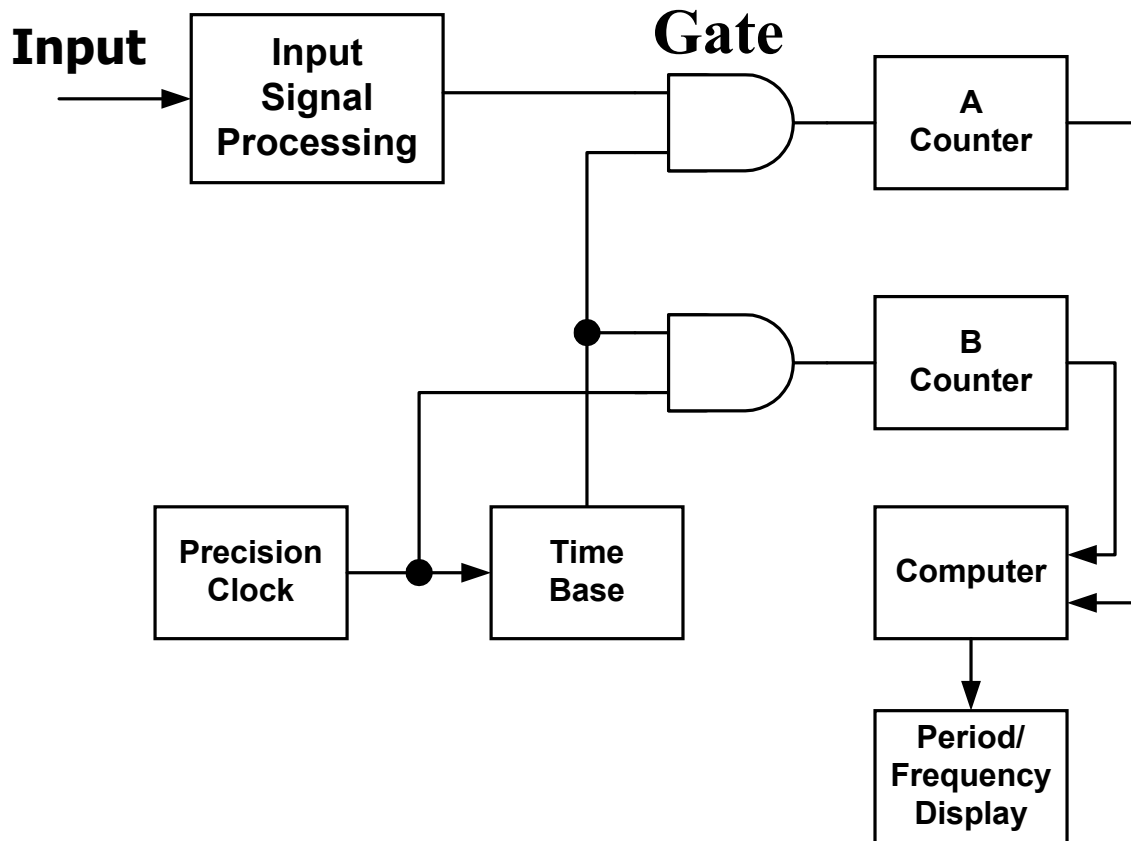
$N$ : Harmonic number

$$\text{Input freq., } f_{\text{in}} = f'_{\text{in}} \pm Nf_c$$

$$\text{Displayed freq.} = f_{\text{in}} \frac{Q}{f_c} = f'_{\text{in}} \frac{Q}{f_c} \pm NQ = f'_{\text{in}} t \pm NQ$$

**Accuracy  $\propto t$ ; ( $NQ$  is constant)**

# Computing Counter



$$\text{Input freq.} = \frac{\text{Count in A}}{\text{Count in B}}$$

$$\text{Input time} = \frac{\text{Count in A}}{\text{Clk freq.}}$$

- ✓ **Opening and Closing gate are controlled from either the input signal or the internal clock.**
- ✓ **Computer will help to determine whether freq./period will be performed.**